Probability Preliminaries

• Set operations

Note the following basic property of unions and intersections of sets $\bigcup_{\epsilon} A_{\epsilon}^{-\frac{r}{2}} = \bigcap_{\epsilon} A_{\epsilon}^{\epsilon}$. Or equivalently: $\bigcup_{\epsilon} A_{\epsilon}^{-\frac{r}{2}} = \bigcap_{\epsilon} A_{\epsilon}^{r}$

o **Proposition**: Let $\{A_{\epsilon}\}$ be a sequence of (measurable) events such that $\mathbb{P}(A_{\epsilon}) = 1$ for all n. Then $\mathbb{P}(\bigcap_{\epsilon} A_{\epsilon}) = 1$.

Proof. First consider that $\left[\bigcap_{i}A_{i}^{T}=\bigcup_{i}A_{i}^{T}\right]$. Then consider that, using the union bound $\mathbb{P}\left[\bigcup_{i}A_{i}^{T}\leq\sum_{j}\mathbb{P}\left\{A_{i}^{T}\right\}\right]=\sum_{i}1-\mathbb{P}\left(A_{i}\right)=\sum_{j}0=0$. The union bound, used in the first line, simply, ratace that if we add the probability of venets without subtracting their intersections, the result will be greater than when considering the union (which leave out intersections).

 $\label{eq:continuous} \begin{minipage}{0.5\textwidth} $Definition (limsup and liminf)$: Let $\{a_i\}$ be a real-value sequence. Then we write $\lim\sup_i a_i = \inf_{a_i} \sup_{a_i>0} a_i$. This is the least upper bound on that sequence. Similarly $\lim\inf_i a_i = \sup_i \inf_{a_i>0} a_i$. Note that these limits need not be finite. $Remarks$:$

- If lim sup_a a_a < a, then a_q < a eventually (ie: for sufficiently large n). If lim sup_a a_a > a, then
 a_q > a infinitely often in other words, there are infinitely many elements in the sequence
 above a.
- $\blacksquare \quad \text{Similarly, } \lim\inf_{a}a_{n}>a\Rightarrow a_{n}>a \text{ ev. and } \lim\inf a_{n}<a\Rightarrow a_{n}<a \text{ i.o. }$
- Definition (limsup and liminf for sets): Let $\{A_n\}$ be a sequence of measurable sets. Then

$$\begin{array}{l} \lim\sup_{n}A_n:=\bigcap_n\bigcup_{n\geq n}A_n=\lim_{m\rightarrow\infty}\bigcup_{n\geq n}A_n\\ \lim\inf_{n}A_n:=\bigcup_n\bigcap_{n\geq n}A_n=\lim_{m\rightarrow\infty}\bigcap_{n\geq n}A_n \end{array}$$

We can interpret these as follows. The lim sup of A_c is the set of events that are contained in infinitely many of the A_c (but not necessarily in all the A_c pust a point – the event could "bounce in and out" of the A_c) [$\lim \sup_i A_i^i - |\omega \in O : \omega \in A_i$, $i \circ i^k$. Similarly, the lim inf of A_c is the set of events that eventually appear in an A_c and then in all A_c past that point. $\{\lim \inf_i A_c^i\} = \{\omega \in O : \omega \in A_c \in A_c \in V\}$. Clearly, if an event is in the $\lim \inf_i B_c$ at one possess infinitely often (because it as the B_c) are B_c and B_c in the B_c point and B_c becomes in sure, A_c .

Remark Take
$$\{A_i, \operatorname{ev}\} = \{\lim \inf_i A_i\}$$
. Then $\{A_i, \operatorname{ev}\}' = \left|\bigcup_n \bigcap_{n \geq n} A_i'\right|$
 $= \bigcap_n \{(\bigcap_{n \geq n} A_i)'\} = \bigcap_n \bigcup_{i \geq n} A_i' = \lim \inf_i A_i' = \{A_i', \operatorname{i.o.}\}$

o Proposition: Let $\{A_a\}$ be a sequence of measurable sets, then $\mathbb{P}(\liminf_{t} A_t) \le \liminf_{t} \mathbb{P}(A_s)$ and $\mathbb{P}(\limsup_{t} A_t) \ge \limsup_{t} \mathbb{P}(A_s)$. (The first statement can be thought of as a generalization of Fatou's Lemma for probabilities).

• Interchange arguments

- Theorem (BDD Bounded Convergence). Let {X_i} be a sequence of random variables such
 that |X_i| ≤ K ≤ ∞ (where K is a deterministic constant) and X_i → X almost surely, then
 E(X_i) → E(X).
- $\begin{array}{lll} \bullet & \textbf{Lemma} & (\textbf{Faton}): & \text{If} & \left\{X_{s}\right\} & \text{is a sequence of non-negative random variables, then} \\ \mathbb{B}(\liminf_{s}X_{n}) \leq \liminf_{s}\mathbb{E}(X_{s}). & (\text{Note: there is no converse for lim sup}). \end{array}$
- Theorem (DOM Dominated Convergence): Let {X_s} be a sequence of random variables such that |X_s| ≤ Y with E(Y) < ∞ and X_s → X almost surely, then E(X_s) → E(X).
- o Prop. (Fubini II): Let $\{X_n\}$ be a sequence with $\mathbb{E}\left(\sum_n |X_n|\right) < \infty$. Then $\mathbb{E}\left(\sum_n X_n\right) = \sum_n \mathbb{E}(X_n)$
- o Definition (u.i): A sequence of random variables $\{X_{\epsilon}\}$ is said to be uniformly integrable (u.i.) if for all $\epsilon > 0$, there exists a $K(\epsilon) < \infty$ such that sup, $\mathbb{B}[|X_{\epsilon}|]: |X_{\epsilon}| > K(\epsilon)$ = sup, $\mathbb{E}[|X_{\epsilon}|]_{\mathbb{F}[|X_{\epsilon}|] = 0}] \le \epsilon$
- o Proposition Let $\{X_a\}$ be a sequence of random variables and suppose $X_a \to X$ almost surely (1) If $\{X_t\}$ are uniformly integrable, then $\mathbb{E}(X_t) \to \mathbb{E}(X)$. In fact, a stronger result applies that $\mathbb{E}[\|X_t X\|] \to 0$. (2) If $X_a > 0$ for all n and $\mathbb{E}(X_t) \to \mathbb{E}(X) < \infty$, then $\{X_t\}$ are u.i.
- $\begin{tabular}{ll} \circ $Prop (Sulficient conditions for u.i.) (1) If up, $\mathbb{E}[X_a]' < \infty$ for some $p > 1$, then $\{X_a\}$ is uniformly integrable, then $\{X_a\}$ is u.i. (3) If $\{X_a\}$ and $\{Y_a\}$ are uniformly integrable, then $\{X_a+Y_a\}$ is u.i. $$$

Kolmogorov's 3-Series Theorem

- o Theorem (Kolmogorov 3-series): Let $\{X_i\}$ be a sequence of independent random variables. Then $\sum_i X_i \text{ converges if and only if for some (and therefore every) } K > 0$, the following condition hold: $(1) \sum_i \mathbb{P}[\|X_i\| > K) < \infty \text{ (clearly, for example, if the } X_i \text{ are IID without bounded support, we'll never be able to satisfy this). This is a statement that the "mass in the tails" must decrease with <math>n$. $(2) \sum_i \mathbb{E}[X_i \|X_i\| \le K] < \infty \quad (3) \sum_i \mathbb{V}a(X_i \|X_i\| \le K) < \infty. \text{ Note that there are no issues of existence of the expected values and the variance in the last two points because these are taken over a finite range namely on <math>X_i \in \mathcal{E}(K,K)$
- Proposition (Z^{nt} version of 3-series theorem): Let {X_s} be independent random variables with
 E(X_s) = 0 for all n. If ∑_n ∇ar(X_s) < ∞, then S_s = ∑_{n=1}^s X_n converges almost surely.

Prop. (Skorohod Representation) Let {X_i} be a sequence of random variables such that X_i ⇒ X. Then there exists a probability space {Ω, F, P} supporting a sequence {X'_i} and X' such that X' ^d X and X' ^d X And X' → X' almost surely.

- Prop. (Continuous Mapping Theorem CMT): Let {X_c} be such that X_c ⇒ X. Let f be a
 function with P(X ∈ D_f) = 0 with _{Bf} being the set of discontinuity points of f. Then f(X_c) ⇒ f(X)
- o Proposition (Converging Together Lemma CTL): If $\{X_i\}$ is a sequence such that $X_i \Rightarrow X$ and $\{Y_i\}$ is a sequence such that $Y_i \Rightarrow a$ (where a is a deterministic constant), then (1) $X_i + Y_i \Rightarrow X + a$ (2) $X_i Y_i \Rightarrow X_i = 0$ (3) $\frac{X_i}{i} \Rightarrow \frac{1}{i} X_i$ provided a = 0.

Introduction to Large Deviation

- $\begin{array}{ll} \circ & \textit{Theorem Let X_1, X_2, \cdots be IID$ with mean μ and such that $M(\theta) = \mathbb{E}(e^{L_1})$ exists for all $\theta \in \mathbb{R}$, and assume & $\mathbb{P}(X_1 = \mu) < 1$. Then for any $a > \mu$, $\frac{1}{\pi}\log \mathbb{P}(S_n > na) \to -I(a)$ Where $I(a) = \sup_{n \in \mathbb{R}} [\delta a \log M(\theta)] = \sup_{n \in \mathbb{R}} |\delta a \sqrt{\theta}|$ \end{array}$
- o Example Let X_i, X_j, \cdots be IID $X(\mu, \sigma^2)$ variables variables. Fix $a > \mu$. We saw, earlier that $P(S_a > na) \le \exp(-nk|\sigma)) = \exp(-nk|\sigma)$. The central limit theorem allows us to "handwave" $S_a = n\mu + \sigma \sqrt{nN}(0,1)$. Using this result, however, we can be more exact —we can find a sequence, such that S_a eventually like below $n\mu + a_a$ a.a. Consider: $P(S_a > n\mu + a_a) \le \exp(-n\frac{N(n+\alpha)}{2\sigma})$. For summability, choose $a_a = \sqrt{2(1+\delta)^2 n\log n}$. This is very close to \sqrt{n} , which we might expect to vortigizen the CLT. $P(S_a > n\mu + a_a) \le n^{-n/\alpha}$. Use BC-1.
- Theorem (Moderate Deviations) Under the conditions of Gramer's Theorem, for any sequence a_s such that (1) $\frac{a_s}{L} \to \infty$ (2) $\frac{a_s}{L} \to 0$, then for any a > 0, $\frac{1}{L^2} \log \mathbb{P}\left(S_s > n\mu + aa_s\right) \to -\frac{1}{L^2}$

Random Walks & Martingales

• Random walks

- $\qquad \qquad \circ \quad \textbf{Definition} \text{ RW is } S_{\pi} = \sum\nolimits_{i=1}^{n} X_{i} \text{ , with the } \left\{ X_{\pi} \right\} \text{ IID, and independent of } S_{0}.$
- $\textbf{Definition} \ (\textbf{Stopping time}) : \textbf{Suppose} \ T \ \text{is a non-negative integer-valued random variable. Then} \ T \ \text{is aid to be a } stopping time \ \text{with respect to an underlying sequence} \ \{X_s\} \ \text{ if, } \{T=k\} \in \mathcal{F}_s \qquad \forall k$
- o Proposition (Wald's First Identity): Let \mathcal{S}_{c} be a random walk $\mathcal{S}_{s} = \sum_{i=1}^{n} X_{i}$, with $\mathcal{S}_{t} = 0$, and let T be a stopping time w.r.t. the sequence $\{\mathcal{F}_{s}^{i}\}$ $(1) X_{i} \geq 0 \Rightarrow \mathbb{R}(S_{p}) = \mathbb{E}(T)\mathbb{E}(X_{i})$ (2) If $\mathbb{E}[X_{i}] < \infty, \mathbb{E}(T) < \infty \Rightarrow \mathbb{E}(S_{p}) = \mathbb{E}(T)\mathbb{E}(X_{i})$

$$\begin{array}{l} \textbf{\textit{Proof.} Let } S_T = \sum_{i=1}^T X_i = \sum_{i=1}^m X_i \mathbb{I}_{\left\{ \subseteq T \right\}} \\ \textbf{Now, let us do both parts:} \end{array}$$

Proof of (i): Let us define $B_n = \bigcap_{i\geq n} A_i$. Then we know that $\cdots \subseteq B_n \subseteq B_{n+1} \subseteq \cdots$. In other words, the sets B_n increase monotonically to

$$B = \bigcup_{n} B_{n} = \bigcup_{n} \bigcap_{n \ge n} A_{n} = \liminf_{n} A_{n}$$

Since the events are increasing, a simple form of monotone convergence gives us that $\mathbb{P}(B_n)/\mathbb{P}(B)$. But we also have that $\mathbb{P}(B_n) \leq \mathbb{P}(A_i) = n \geq m$ because B_m is the intersection of all events from A_n onwards, so its probability is less than or equal to the probability of any single event. Thus $\mathbb{P}(B_n) \leq \min_{t_i \in \mathbb{P}}(A_i) \Rightarrow m_{B_n} \mathbb{P}(B_n) \leq \min_{t_i \in \mathbb{P}}(A_i) \Rightarrow \mathbb{P}(B_n) \leq \mathbb{P}($

Borel-Cantelli Lemmas & Independent

Proposition (First Borel-Cantelli Lemma) Let {A_i} be a sequence of measurable events such
that ∑_i P(A_i) < ∞. Then P(A_i io) = 0. In other words, P(lim sup_i A_i) = 0. ¹ We offer two proofs—
the first is somewhat mechanical, the second is more intuitive.

$$\begin{array}{ll} \textbf{\textit{Proof}} & (\textbf{\textit{version}} & 1): & \text{Consider} & \text{that} & \lim\sup_{s} A_{s} = \bigcap_{n} \bigcup_{s \geq n} A_{s} & \text{such} \\ \Big[\lim\sup_{s} A_{s} \Big] \leq \mathbb{P}\Big[\bigcup_{s \geq s} A_{s} \Big] \leq \sum_{s \geq n} \mathbb{P}\Big[A_{s} \Big) \to 0 \text{ As required.} \end{array}$$

The second proof will require a lemma:

Lemma (Fubini's): If $\{X_s\}$ is a sequence of real-valued random variables with $X_s \ge 0$, then $\mathbb{E}(\sum_s X_s) = \sum_s \mathbb{E}(X_s)$ (which could be infinite). This is effectively a condition under which we can exchange a summation and an integration.

Proof (version 2): Let $X_i(\omega) = \mathbb{I}_{\mathcal{K}} = \begin{bmatrix} 1 & \text{if } \omega \in A_i \\ \text{otherwise} \end{bmatrix}$. Note that $\mathbb{E}(X_i) = \mathbb{P}(A_i)$. We also have that $\sum_i \mathbb{P}(A_i) = \sum_i \mathbb{E}[\mathbb{I}_{\mathcal{K}_i}] = \mathbb{E}(\sum_i \mathbb{I}_{\lambda_i}) < \infty$. This means that the random variable $\sum_i \mathbb{I}_{\lambda_i}$ must be less than or equal to infinity for every outcome in Ω ; in other words $\sum_i \mathbb{I}_{\lambda_i} < \infty$. a.s. This means that $\mathbb{I}_i = \mathbb{I}$ only finitely many times. So, A_i occurs only finitely offer

o Definition (independence): A sequence of random variables $\{X_1, \cdots, X_s\}$ are independent iff $\mathbb{P}(X_1 \leq x_1, \cdots, X_s \leq x_s) = \prod_{s} \mathbb{P}(X_1 \leq x_l)$ for all $x_1, \cdots, x_s \in \mathbb{R}$.

It might not be clear that the statements P(A, i.a.) = 0 and $P(\lim \sup_i A_i) = 0$ are equivalent. To see this more clearly, note that the first statement is simply a shorthand for $P(a \in \Omega : \omega \in A, i.a.) = 0$. This is clearly identical, by definition, to $P(\lim_i u_i A_i) = 0$.

- o Example. Set $X_i = Y_k/n$, where the Y_a are IID exponential random variables with mean 1. Does the sum $S_i = \sum_i X_i$ converge? The deterministic series 1/n does not converge, and we woode whether the exponential variable will be close enough to 0 often enough ϵ on ϵ^{-1} that In light of the result we derived in the previous lecture (that draws from an exponential will be arbitrarily large infinitely often) one might expect this series not to converge. First condition $\mathbb{P}[X_i|X_i] \times K) = \mathbb{P}[X_i > K] = \mathbb{P}[X_i > K]$ and the number that condition is therefore met. Second conditions $\mathbb{E}[X_i, X_i] \times K] = \mathbb{E}[\frac{X_i}{K_i}, X_i > K] = \mathbb{E}[X_i, Y_i < K]$. But we note that $\mathbb{E}[X_i, Y_i < K] = K$ $\mathbb{P}[x_i > K] = \mathbb{P}[x_i > K]$. But we note that $\mathbb{E}[X_i, Y_i, X_i] \leq K$ $\mathbb{P}[x_i > K]$ and $\mathbb{P}[x_i > K]$ are therefore, that condition 2
- is violated, because the sum of 1/n diverges. So, as we expected, S_c does not converge almost nurely, or Example: Set $X_c = Y_c/g$, where the Y_c are IID random variables with $P(Y_c = 1) = P_c/P(y_c = 1) = P_c$. Once again, we wented whether $S_c = \sum_{n=1}^{\infty} X_c$ converges. The intuition here is that the deterministic series $\sum_{n} (-1)^n / n$ does converge Our version is this sum, but instead of deterministically flipping between positive and negative, we randomly satich between positive and negative. We wonder whether this vill "spoil" the convergence. We fix K = 0 (say K = 1) and test the three conditions: First conditions $P(X_k) > 1 0$. So clearly, the sum does converge. Second conditions $E(X_c | Y_k | \le 1) = \frac{1}{n} E(Y_c | Y_k | \le n) = \frac{1}{n} E(Y_c) = \frac{2n-1}{n}$. We know, however, that $\sum_k d$ diverges, so the infinite sum of these expectations only converges if $p = V_0$, in which case the numerator is 0. We therefore restrict our attention to that case. Third condition (assuming $p = V_0$) $V_{2k}(X_c | X_k | \le 1) = \frac{1}{n^2} V_{2k}(Y_c | Y_k | \le n) = \frac{1}{n^2} V_{2k}(Y_c) = \frac{2(p^2)^2 0}{n^2}$. The infinite sum of the variances is therefore finite.
- Example: Set $X_i = Y_i / \sqrt{n}$, where Y_i are IID random variables with probability % of being 1 and probably % of being −1, Again, the determinative sum $\sum_i (-1)^i / \sqrt{n}$ converges, and we wender whether adding randomness will make a difference. Since, in this case, $\mathbb{E}(X_i) = 0$, we can simply apply the second form of the 3-suits theorem: $\nabla \alpha_i (X_i + |Y_i| \le 1) = \frac{1}{n} \nabla \alpha_i (X_i + |Y_i| \le n) = \frac{\mathbb{E}(X^i)}{n}$ The infinite sum of these variances clearly diverges, and so S_i does not converge.

• The Strong Law of Large numbers

- Theorem (SLLN): Let $\{X_n\}$ be IID with $\mathbb{E}[X_1] < \infty$, then $\frac{1}{n} \sum_{k=1}^{n} X_k \to \mathbb{E}[X_1]$
- $\circ \quad \textit{(Cesaro Sum Property): } \left\{ a_{\scriptscriptstyle k} \right\} \text{ be real valued sequence } a_{\scriptscriptstyle n} \rightarrow a_{\scriptscriptstyle n}. \text{ Then } \frac{1}{n} \sum_{\scriptscriptstyle k=1}^{n} a_{\scriptscriptstyle k} \rightarrow_{\scriptscriptstyle k \rightarrow \infty} a_{\scriptscriptstyle n}.$
- o (Kronecker's Lemma): $\{a_n\}$ real valued sequence. Then $\sum_{k=1}^{\infty} \frac{a_k}{k}$ converges $\Rightarrow \{\frac{1}{n}\sum_{k=1}^{n} a_k \to 0\}$
 - First part: $X_i \geq 0$, and indicators are always positive, so by Fubini I, we can interchange the expectation and the sum $\mathbb{E}(S_r) = \sum_{i=1}^n \mathbb{E}\left(X_i \mathbb{E}_{[i:j]}\right)$. Consider, however, that $\mathbb{E}_{[P_S]} = 1 \mathbb{I}_{[P_S]} = 1 \mathbb{I}_{[P_S]} = 1 \mathbb{I}_{[P_S]} = 1$. Thus $\mathbb{E}(S_r) = \sum_{i=1}^n \mathbb{E}\left\{X_i \mathbb{E}_{[i:j]} + \mathbb{E}_{[i:j]}\right\} = \sum_{i=1}^n \mathbb{E}\left\{\mathbb{E}_{[i:j]} \times \mathbb{E}\left[X_i + \mathbb{E}_{[i:j]} \times \mathbb{E}\left[X_i + \mathbb{E}_{[i:j]} \times \mathbb{E}\left[X_i + \mathbb{E}_{[i:j]} \times \mathbb{E}\left[X_i + \mathbb{E}$
 - Second part: Triangle inequality $|S_r| \le \sum_{i=1}^r |X_i|$. By part 1, however $\mathbb{E}[\sum^r |X_i|] = \mathbb{E}[T]\mathbb{E}[X_i] < \infty$. The result then follows by Fubria II.
- o Proposition (Wald II): Suppose $\{X_i\}$ are IID bounded random variables, and $\mathbb{E}(X_i) = 0$, $\mathbb{E}(X_i^2) = \sigma^2.$ Let T be a stopping time with respect to $\{\mathcal{F}_a\}$, and such that $\mathbb{E}(T^3) < \infty$. Then $\mathrm{Var}(S_T) = \sigma^2 \mathbb{E}(T)$

• Martingale.

o Consider that if we let $D_{\rm e}=M_{\pi}-M_{\rm e-1}$, we can write $M_{\rm e}=\sum_{i=1}^n D_i+M_0$

Optional Stopping Theorem for Martingale

$\mathbb{E} \big[\lim\nolimits_{n \to c_*} M_{T \wedge n} \big] = \lim\nolimits_{n \to c_*} \mathbb{E} \big[M_{T \wedge n} \big]$

- o Corollary I. Let $\{M_*: n \geq 0\}$ be a martingale with respect to $\{\mathcal{F}_i\}$ and T be a stopping time such that T is bounded (in other words, there exists a $K < \infty$ such that $\mathbb{P}(T < K) = 1$), then $\mathbb{E}(M_*) = \mathbb{E}(M_*)$.
- o Corollary II. Let $|M_{\tau,\alpha}| \le Z$, with $\mathbb{E}(Z) < \infty$. Then by dominated convergence, the interchange holds and $\mathbb{E}(M_\tau) = \mathbb{E}(M_\phi)$.
- o Corollary III. Let $\{M_x: n \geq 0\}$ be a martingale with respect to $\{\mathcal{E}_i\}$ and T be a stopping time such that $\mathbb{E}(T) < \infty$. Provided the martingale differences are uniformly bounded ($\mathbb{E}[\|D_i\||\mathcal{E}_{i-1}] \leq C < \infty$), then $\mathbb{E}(M_2) = \mathbb{E}(M_2)$.

 $\begin{array}{lll} \textit{Proof} & \text{We} & \text{have} & M_{T_{10}} = \sum_{i=1}^{T_{10}} D_i + M_q \cdot M_b & \text{is integrable}. & \text{Now consider that,} \\ \left[\sum_{i=1}^{T_{20}} D_i \right] \leq \sum_{i=1}^{T_{20}} \left|D_i\right| \sum_{i=1}^{\infty} \left|D_i\right| \mathbb{I}_{\{\Gamma_{20}\}} & \text{. tet us now take expectations. By Fubini I, we can then swap the expectation and sum, since the summands are positive} \end{array}$

$$\mathbb{E} \sum\nolimits_{i=1}^{\infty} \left| D_i \right| \mathbb{I}_{\left\{T \geq i\right\}} = \sum\nolimits_{i=1}^{\infty} \mathbb{E} \left| \left| D_i \right| \mathbb{I}_{\left\{T \geq i\right\}} \right| = \sum\nolimits_{i=1}^{\infty} \mathbb{E} \left| \mathbb{I}_{\left\{T \geq i\right\}} \mathbb{E} \left| \left| D_i \right| \mid \mathcal{F}_{n-1} \right| \right|$$

Since the martingale differences are uniformly bounded by C, this is $\leq C\mathbb{E}(T)$. As such, $|M_{Tr_0}| \leq C\mathbb{E}(T) + |M_0| |M_0$ is integrable, and by the statement of the theorem, $\mathbb{E}(T) < \infty$. As such, martingale bounded by integrable variable,

Defininition (independence): $\{A_1, \dots, A_s\}$ are said to be independent if and only if the sequence or random variables $\{\mathbb{I}_1, \dots, \mathbb{I}_s\}$ are independent.

o Proposition (second Borrel-Cantelli Lemma): Let $\{A_s\}$ be a sequence of independent measurable events such that $\sum_{i} \mathbb{P}[A_i] = \infty$, then $\mathbb{P}[A_i \mid i, o] = 1$.

Proof. We showed in a remark above that $\{A_c, i, o\}' = \{A'_c, er\} = \bigcup_a \bigcap_{c \geq a} A'_c$. Let us fix $m \geq 1$. Then using $1 - x \leq c''$, we get $\mathbb{P}\left(\bigcap_{c \geq a} A'_c\right) = \prod_{c \geq a} \mathbb{P}\left(A'_c\right) = \prod_{c \geq a} 1 - \mathbb{P}\left(A_c\right) \leq \prod_{c \geq a} e(-\mathbb{P}(A_c)) = \exp\left(-\sum_{c \geq a} \mathbb{P}(A_c)\right) = 0$. But we have that

 $=\prod_{i\geq n}1-\mathbb{P}\left(A_{i}\right)\leq\prod_{n\geq n}\exp\left(-\mathbb{P}(A_{i})\right)=\exp\left(-\sum_{n\geq n}\mathbb{P}(A_{i})\right)=0.\quad\text{But}\quad\text{we}\quad\text{have}$ $\mathbb{P}\left(\bigcup_{n}\bigcap_{n\geq n}A_{i}^{n}\right)\leq\sum_{n}\mathbb{P}\left(\bigcap_{n\geq n}A_{i}^{n}\right)=0.\quad\text{As required}.\quad\blacksquare$

Notions of convergence

- $\begin{array}{ll} \text{O} & \textbf{\textit{Definition (convergence almost surely)} \ X_s \to X \ \text{almost surely if} \ \mathbb{P}\left\{\omega \in \Omega \colon X_s(\omega) \to X(\omega)\right\} = 1 \\ \\ \text{. More generally,} \ \left\{X_s\right\} & \text{converges almost surely if} \ \mathbb{P}\left(\limsup_s X_s = \liminf_s X_s\right) = 1 \\ \end{array}$
- o Example: Consider the sequence $X_n = \frac{1}{4}U[0,1]$. We claim that $X_n \to 0$ almost surely. **Proof.** In this case, $\Omega = [0,1]$. For any ω we might drawn, we will find $0 \le X_n(\omega) \le \frac{1}{n} \to 0$. As required.
- $\begin{array}{lll} & \textbf{Definition} & \textbf{(convergence in probability):} & X_n \xrightarrow{} X & \text{as} & n \to \infty & \text{if, for all} & \varepsilon > 0. \\ & \mathbb{P}\left(\left| X_n X \right| > \varepsilon \right) \to 0 & \text{as} & n \to \infty & \end{array}$
- o Definition (convergence in expectation) also called L_1 convergence. We say that $X_a \rightharpoonup_{b_1} X$ as $n \rightarrow \infty$ if $\mathbb{B}\left[X_a X\right] \rightarrow 0$ as $n \rightarrow \infty$.
- $\circ \quad \pmb{Claim} \ \, X_n \to_{\mathbb{Z}_q} X \ \, \text{implies that } \mathbb{E} \left| X_n \right| \to \mathbb{E} \left| X \right| \ \, \text{and} \ \, \mathbb{E}(X_v) \to \mathbb{E}(X).$
- $\circ \quad \textit{Claim:} \text{ If } X_{\scriptscriptstyle 0} \to_{\underline{\iota}_{\scriptscriptstyle 1}} X \text{ then } X_{\scriptscriptstyle 0} \to_{\scriptscriptstyle p} X \, .$

 $\textbf{\textit{Proof.}} \text{ Fix } \varepsilon > 0 \text{ , use Markov's Inequality } \mathbb{P} \left(\!\! \left| X_s - X \!\! \right| > \varepsilon \right) \! \leq \mathbb{E} \left(\!\! \left| X_o - X \!\! \right| \right) / \varepsilon \to 0$

Example: Let X_c be a sequence of IID random variables with exponential distribution with parameter 1. We will prove that lim sup(X_c / log n) = 1 a.c.

Proof. Take $\varepsilon > 0$. Consider $\mathbb{P}\left(X_i > (1+\varepsilon)\log n\right) = e^{-2\pi\varepsilon\log n} = 1/n^{2\pi}$. Thus $\sum_{i} \mathbb{P}\left(X_i > (1+\varepsilon)\log n\right) < \infty$. B) $\mathrm{BG}(1,\mathbb{P}\left(X_i > (1+\varepsilon)\log n, (\alpha) = 0$. So, $X_i \le (1+\varepsilon)\log n$ or, a.s. and so $\overline{\lim\sup_{i \to \infty} \sum_{i \le j \le n} 1} \le 1+\varepsilon \overline{\lim\sup_{i \to \infty} \mathbb{P}\left(X_i > (1-\varepsilon)\log n\right)} = \frac{1}{n^{1-\varepsilon}} \Rightarrow \sum_{i} \mathbb{P}\left(X_i > (1-\varepsilon)\log n\right) = \infty$, so by BG-2 and independence of the $X_n \mathbb{P}\left(X_i > (1-\varepsilon)\log n\right) = 1 \Rightarrow \overline{\lim\sup_{i \to \infty} \frac{X_i}{n}} > 1-\varepsilon$ a.s.

o Exemple: Let $\{X_i\}$ be an IID sequence of random variables with $\mathbb{E}(X_i) = 0$ and $\mathbb{E}(X_i^0) = \sigma^2 < \infty$. Let $S_i = \sum_{i=1}^n X_i$, and consider S_i Ia_i with $a_i = \sqrt{n} \left(\log n\right)^{\frac{n}{2}}$. $\log n$ grows extremely slowly, so this is really very close to a \sqrt{n} growth. Consider that $\operatorname{Var}(X_i / a_i) = \sigma^2 / \sqrt{n} (\log n)^{n/n}$, and this implies that $\sum_i \operatorname{Var}(\frac{1}{\gamma_i}) < \infty$. Thus, by the Kolmogorov 3-series thereone, $\sum_i \frac{1}{\gamma_i}$ converges almost sarely, and by Konecken's Lemma, this means that $S_i / a_i = 0$. Thus, we see that even with such a small-growing a_i , an almost-sure result still holds. However, it is interesting to note that if we take $a_i = \sqrt{n}$ (slightly smaller), then no almost sure result holds anymore. The best we can say is

$S_n/\sqrt{n} \rightarrow \sigma N(0,1)$. • Weak convergence & the Central Limit Theorem

- Definition (Weak convergence): A sequence of random variables {X_s} is and to converge weakly
 to a random variable X, denoted X_s ⇒ X as n → ∞, if and only if E[f(X_s)] → E[f(X)] for all
 bounded continuous functions f. Comments if X, → X almost surely, then f(X_s) → f(X), because
 f is continuous, and E[f(X_s)] → E[f(X)], by bounded convergence (since the functions are bounded).
 Thus, almost rule convergence imbles weak convergence.
- Definition (Weak convergence): A sequence of real valued random variables {X_n} convergence weakly to X if and only if F_n(x) → F(x) for all continuity points of F, where X_n F_n and X F.
- o Definition (Tightness): A sequence of random variables $\{X_i\}$ with corresponding distribution functions $\{F_i\}$ is said to be tight if $\forall e > 0$, $\exists K(e) < \infty$ at. $\sup_i \mathbb{P}\left[\|X_i\| > K(e)\right] \le e$. Equivalently $\sup_i \left[1 F_i\left(K(e)\right)\right] \le \varepsilon$. Comment A sufficient condition for tightness if $\sup_i \mathbb{E}\left[|X_i| < \infty$. To see why, with K = 0, and consider that by Markov's Inequality $\mathbb{P}\left[\|X_i\| > K\right] \le \frac{\|X_i\|}{\nu} \le \frac{\|X_i\|}{2} \le \frac{\|V_i\|}{\nu}$.
- Proposition: Let {X_s} be a sequence of random variables (i) If X_s = X, then {X_s} is tight (2) If {X_s} is tight. Then there exists a subsequence {n_s} such that {X_s} converges weakly. This is somewhat isomorphic to the concept of compactness in real analysis.
- o Definition (Characteristic Function). A characteristic function (CF) of a random variable X is given by $\varphi_L(0) = \mathbb{E}[\exp(\partial X)]$ $\theta \in \mathbb{R}$. Remarks (1) $\varphi_L(0) = 1$ (2) $|\varphi_L(0)| \leq 1$, because by Jensen's inequality, $|\varphi_L(\theta)| \leq |\mathbb{E}[\exp(\partial X)]] = 1$ (3) $|\varphi_L^{(0)}(0)| = r^*\mathbb{E}(X^n)$, provided $\mathbb{E}[X] \subset \infty$. (4) If X and Y has independent, $\varphi_{L^{(0)}}(0) = \varphi_L(0)$, (6) though the converse is false.
- o Proposition (Levy characterization theorem): Let $\{X_i\}$ be a sequence of random variables with distribution functions $\{F_i\}$. If $\psi_{X_i}(\theta) \to \psi(\theta)$ for all $\theta \in \mathbb{R}$ and $\psi(\theta)$ is continuous at 0 [kind of a tightness condition]. Then $X_i \to X$ and X has characteristic function $\psi(\theta)$.
- Odds & Ends

Martingale Limit Theory & Concentration Inequalities

o Proposition (Martingale SLLN). Let $\{M_n: n \geq 0\}$ be a maximale with respect to $\{\mathcal{F}_n\}$ such that $\sup_{n \geq 0} \mathbb{E}(D_n^2) < \infty$ (this, as we saw above, is a requirement for the increments to be uncorrelated). Then $\frac{n_n}{2} \to 0$ a.s.

Proof: Put $\tilde{M}_a = \sum_{i=1}^{n} \frac{D_i}{\lambda_i}$ (where, as usual $D_i = M_b - M_{b-1}$). Clearly, $\tilde{M}_a \in \mathcal{F}_a$, and

$$\begin{split} \mathbb{E}[\hat{M}_{i}\mid\mathcal{F}_{-i}] &= \mathbb{E}[\sum_{i=1}^{i+1}\frac{p_{i}}{k^{2}}+\mathcal{F}_{-i}\mid\mathcal{F}_{-i}] = \sum_{i=1}^{i+1}\frac{p_{i}}{n^{2}}|\hat{D}_{i}\mid\mathcal{F}_{-i}] = \hat{M}_{-1} \text{ and } \mathbb{E}[\hat{M}_{i}|<\infty \text{ for all }n, \text{ due to the conditions on the second moments of }D_{o}. \text{ Thus, it is a mattingule. Now } \mathbb{E}[\hat{M}_{i}]^{2} = \mathbb{E}[\sum_{i=1}^{i+1}\frac{p_{i}^{2}}{k^{2}}] + \mathbb{E}[\sum_{i=1}^{i+1}\frac{p_{i}^{2}}{i^{2}}] \text{ The second term is equal to 0, since the }D \text{ are uncorrelated.} \\ \mathbb{E}[\hat{M}_{i}]^{2} \leq \sum_{i=1}^{i+1}\frac{mp_{o,i}}{k^{2}} + \mathbb{E}[\sum_{i=1}^{i+1}\frac{p_{i}^{2}}{i^{2}}] < \infty. \text{ This implies that } \sup_{i=1}^{i+1}\mathbb{E}[\hat{M}_{i}]^{2} < \infty \Rightarrow \sup_{i=1}^{i+1}\mathbb{E}[\hat{M}_{i}]^{2} < \infty. \text{ If } \infty, \text{ by } \text{ the Muttingule Convergence Theorem. } \hat{M}_{i} \rightarrow \hat{M}_{o}, \text{ a.s. } \text{ Now. let} \\ A = \left\{\omega : \sum_{i=1}^{i+1}\frac{p_{i}^{2}\omega}{i} \rightarrow M_{o}(\omega)\right\} \qquad , \mathbb{F}(A) = 1 B = \left\{\omega : \frac{1}{n}\sum_{i=1}^{i+1}D_{i}(\omega) \rightarrow 0\right\}. \text{ By Kroenecker's Lemma} \end{split}$$

 $A \subseteq B$. Thus, P(B) = 1. This proves our Theorem.

Proposition (Central Limit Theorem for Martingales): Let $\{M_n : n \ge 0\}$ be a martingale with respect to $\{\mathcal{F}_n^i\}$ and put $V_n = \max_{Q \in \mathcal{Q}} |D_n^i|$. If $(1) \sup_{n \ge 0} \frac{n^{2(i)}}{n} \sim c$ $(2) |V_n^i| \sqrt{n} \Rightarrow 0$ (3) $\frac{1}{2} \sum_{i=1}^n \mathcal{Q}^i \Rightarrow o^i$ (deterministic and finite). This makes our martingale "similar" to a random walk.

$$\begin{split} & \text{Them}_{\overline{\mathcal{L}}}M_n = \sigma N(0,1) \\ & \text{O Proposition (Axuma-Hoeffding Inequality): Let } \left\{M_n: n \geq 0\right\} \text{ be a maximpale with respect to} \\ & \left\{\mathcal{F}_n\right\} \quad \text{such} \quad & \text{that} \quad \left|M_n - M_{n-1}\right| = \left|\mathcal{D}_n\right| \leq c, \ \forall n \\ & \text{\mathbb{R}} \left(\left|M_n - M_n\right| \geq \lambda\right) \leq 2\exp\left\{-\frac{V}{N^{\infty} - \delta}\right] \end{split}$$

 $\begin{aligned} & \| \mathbf{u}_n^* - \mathbf{m}_{\mathbf{q}} \| \leq \kappa \| \leq \cos(\frac{1}{2 \sum_{i \leq n} d_i}) \\ & & \text{Remark: Suppose that } \| D_n^i \| \leq \epsilon \ \forall k, \text{ then we can re-write this as } \mathbb{P} \left(\| M_n - M_{\mathbf{q}} \| \geq \lambda \right) \leq 2 \exp \left[-\frac{\lambda^2}{2 \epsilon^2 \kappa} \right] \\ & \text{or } & \mathbb{P} \left(\| M_n - M_{\mathbf{q}} \| \geq \epsilon \sqrt{\kappa} \right) \leq 2 \exp \left[-\frac{\kappa^2}{2} \right] & \text{Or, choosing } \lambda = \sqrt{\kappa n \log n} \ , \text{ we obtain } \\ & \mathbb{P} \left(\| M_n - M_{\mathbf{q}} \| \geq \sqrt{\kappa n \log n} \right) \leq 2 \exp \left[-\frac{\kappa \log n}{2 \epsilon^2} \right] & \text{Choosing, for example, } \kappa = 4\epsilon \text{ produces a summable } \\ \end{aligned}$

sequence, which can be used to obtain an almost sure result. Stochastic stability

 $\begin{array}{c} \circ \quad \textbf{\textit{Proposition}. Let } \left\{ X_s : n \geq 0 \right\} \text{ be an inreducible markov chain on a countable state space } \mathcal{S}^s. \text{ Let} \\ K \subseteq \mathcal{S} \text{ be a set containing a finite number of states. Then, if there exists a function } g: \mathcal{S} \to \mathbb{R}_+ \text{ such } \\ \end{array}$

- $(\text{recall} \qquad \mathbb{E}_{\varepsilon}[\cdot] = \mathbb{E}[\cdot \mid X_0 = x]) \qquad \mathbb{E}_{\varepsilon}g(X_1) g(x) \leq -\varepsilon \quad \forall x \in \overline{K} \text{ and some } \varepsilon > 0 \qquad \text{and} \qquad \mathbb{E}[\cdot] = \mathbb{E}[\cdot \mid X_0 = x]$ $\mathbb{E}_{s}g(X_{1})<\infty \quad \forall x\in \mathcal{K} \text{ Then } \left(X_{n},n\geq 0\right) \text{ is positive recurr}$
- "Application": Consider the stochastic system $X_{e+1} = \alpha X_e + Z_{e+1}$ with $\left\{Z_e\right\}$ iid and $X_b = x$. We want conditions on α and distributions of Z such that X_n is stable. Use g(x) = |x| and $\mathbb{E}_s g(X_i) = \mathbb{E}_s \left| \alpha x + Z_i \right| \leq \left| \alpha \right| \left| x \right| + \mathbb{E} \left| Z_i \right|. \text{ So if } \mathbb{E} \left| Z_i \right| < \infty \text{ and } \left| \alpha \right| < 1 \text{, then we might be able to make the sum of the$ this work, because we would then have $\mathbb{E}_z g(X_1) - g(z) \le \left(|\mathbf{o}| - 1\right)|x| + \mathbb{E}(Z) \le -\varepsilon$ provided $|X| \ge \frac{|\mathbf{g}|^2 + \varepsilon}{1 + 1}$

- Definition: $\{X_n\}$ is a sub-martingale with respect to $\{\mathcal{F}_n\}$ if (1) $X_n \in \mathcal{F}_n$ (2) $\mathbb{E}(X_n) < \infty$ (it is often convenient to work with the stronger condition $\mathbb{E}[X_{\epsilon}] < \infty$]. (3) $\mathbb{E}[X_{\epsilon+1} \mid \mathcal{F}_{\epsilon}] \geq X_{\kappa}$ \leq gives a super-
- martingale, = gives a martingale]. Implies the weaker property $\mathbb{E}[X_{n+1}] \ge \mathbb{E}[X_n]$ Remarks: A convex function of a martingale is a submartingale. (2)An increase submartingale is a submartingale. **Proof.** (i) and (ii) are simple. $\mathbb{E}[f(X_{cat}) | \mathcal{F}_c] \ge f(\mathbb{E}[X_{at}, | \mathcal{F}_c]) \ge f(X_c)$.
- **Example:** Let $S_i = \sum_{i=1}^n X_i$, where the X_i are IID with $\mathbb{E}(X_i) = 0$, $\mathbb{E}[X_i] < \infty$
 - $\circ \quad S_n \text{ is a martingale } \|\mathbb{E} \|S_i\| \leq n \mathbb{E} \|X_i\| \| \text{ (the } mcan \ martingale)}.$
 - If Var(X_c) = σ² < ∞ , X_c² − σ²n is a martingale (the variance martingale).
- Example (the exponential martingale): Let $\varphi(\theta) = \mathbb{E}(e^{\theta X_1})$. $M_{\epsilon} = e^{\theta \theta_{\epsilon}} / \varphi^{\epsilon}(\theta)$ is a martingale. For example, if $S_n = \sum_{i=1}^n X_i$ is an asymmetric random walk with $p = \mathbb{P}(X_i = 1) = 1 - \mathbb{P}(X_i = -1)$, then $M_{-} = \left(\frac{1-p}{r}\right)^{\zeta_{+}}$ is an exponential martingale, with $c^{\theta} = \frac{1-p}{r}$ and $\varphi(\theta) = 1$.
- Example: Suppose an urn starts with one black and one white ball. We pull out balls from the urn, and return them to the urn with another, new ball of the same color. Y_n , the proportion of white balls after n
- Example: Let {X_a} be a Markov Chain with transition matrix P(x, y) and let h(x) be a bounded function with $h(x) = \sum_{n} p(x,y)h(y)$. $\{h(X_n)\}$ is then a martingale.

Optional stopping

- . Definition (stopping time): If T is an integer valued random variable, we say it is a stopping time with respect to a filtration \mathcal{F}_{ϵ} if $\{T=n\}\in\mathcal{F}_{\epsilon}$ for all n (or $\{T\leq t\}\in\mathcal{F}_{\epsilon}$ for all t, in continuous time) Remark If T_1 and T_2 are stopping times, so are $T_1+T_2,T_1\wedge T_2,T_1\wedge T_2$.
- Theorem: If $\{X_i\}$ is a (sub)martingale and T is a stopping time, $\{X_{\gamma,\alpha}\}$ is also a (sub)martingale. If $\{X_{\gamma}\}$ is u.i., so it $\left\{X_{T \land x}\right\}$. **Proof.** Write $X_{T \land x} = \sum_{b=0}^{s-1} X_b \mathbb{I}_{\{T=0\}} + X_a \mathbb{I}_{\{T>s-1\}}$. Clearly, this is \mathcal{F}_a measurable, and $\left|X_{\tau,*}\right| \leq \sum_{i=1}^{n-1} \left|X_i\right| + \left|X_s\right| \text{ so it is integrable. Conditioning follows. } \underline{\overline{u.t}} \text{ : to show u.i., first note that } \left\{X_{\tau,*}^*\right\} \text{ is also follows.}$ also a submartingale, and so $\mathbb{E}(X_{2\times a}^+) \leq \mathbb{E}\left|X_*^+\right| \leq \mathbb{E}\left|X_*\right|$. Taking limits, $\sup_a \mathbb{E}(X_{7\times a}^+) \leq \sup_a \mathbb{E}\left|X_a^+\right| < \infty$ [the last inequality follows by u.i. of $\left\{X_n\right\}$]. By the theorem in the martingale conve
- $\bullet \quad \textit{Example} \text{ Let } X_1 U[0,1], \text{ and } X_u \mid X_{u-1} U[0,X_{v-1}]. \text{ Let } Y_u = 2^o X_u. \text{ We can write } X_u = U_1 \cdots U_u \text{ with each } X_u$ U IID U[0,1]. This is a martingale, and, by the SLLN, $\frac{1}{n} \log Y_n = \log 2 + \frac{1}{n} \sum_{i=1}^{n} \log U_i \rightarrow \log 2 + \mathbb{E}(\log U_i) < \infty$ a.s. So $Y_n \to 0$. Note, however, that $\operatorname{Var}(X_n) = \left(\frac{1}{2}\right)^n - 1$. Again, the variance blows up. \square
- ... Theorem: When $\{X_e\}$ is a martingale, the following are equivalent (1) X_e is u.i. (and therefore almost surely) (2) $X_a = \int_{\mathbb{R}_+} X$ (3) X_a can be written as a Doob martingale; $X_a = \mathbb{E}[X \mid \mathcal{F}_a]$, with $\mathbb{E}[X] < \infty$. For submartingales, only (i) and (ii) are equivalent.
- . Example (Polua's Urn): Consider the example of Polya's Urn, discussed above. Let X, be the proportion fired balls in the urn after draw n. By symmetry, $\mathbb{E}(X_n) = \frac{1}{2}$.

Queuing

 $\circ \quad \omega = \left\{ (t_*, S_*) \colon n \in \mathbb{Z} \right\}. \ S_* \text{ is work, } t_* \text{ is arrival time. Processing at unit rate. } W_i(\omega) \text{ is work in system}$ at time t. $X_i^*(\omega)$ is work in system at time t if empty at s. $X_i'(\omega) = \lim_{z \to \infty} X_i^*(\omega)$ exists because

 $\textbf{\textit{Proof.}} \ \ \text{Fix} \ \ t \in \mathbb{R} \ \ \text{and} \ \ \omega \in \Omega \ \ \text{and define} \ \ T^*_r(\omega) = \sup \left\{ \tau < t : X^*_r(\omega) = 0 \right\}; \ \text{last empty time before time}$

Show $\rho < 1 \Rightarrow T_r^{-\infty} > -\infty$ a.s. We do this by contradiction; suppose $\rho < 1$ and $T_r^{-\infty} = -\infty$ $\omega \quad \text{of sample paths. From the second line above, we have, } X_i^s = \sum_{i \in \mathbb{Z}} S_i \mathbb{1}_{\left\{ t_i \in \mathbb{F}_i^s / \frac{t_i}{2} - \left(t - T_i^s\right) \right.} \text{Now,}$ however, that $X_i^* \ge 0$ (there can never be negative work in the system), and so, dividing by $t - T_i^*$ throughout, we obtain $\frac{\sum_{i \in S_i} \frac{1}{2} \sqrt{n_i T_i T_i}}{2} \ge 1$. Note that if we were to replace T_i^a with s_i the LHS of this ion would form a sequence with limit to ρ as $s \to -\infty$. By the definition of a limit, however this is also true for any subsequence of that sequence. But since we have assumed $T^i_i \to -\infty$ as

$= \frac{1}{1+\varepsilon} \frac{A(t)}{t} \left\{ \frac{\sum_{s=0}^{N(t)} \theta_n}{A(t)} - \frac{\sum_{s=0}^{N(t)} \theta_n}{A(t)} \right\} \xrightarrow{1+\varepsilon} A_{gain}, \text{ the first term tends to } \lambda \text{ by assumption 1. The}$

second term tends to $\overline{\theta}$ by a similar logic as above, and by noting that since $N(s) < \infty$, the second term in brackets tends to 0. As such, we get $\liminf_{t\to\infty}\frac{1}{t}\int_0^t N(\varepsilon)\ \mathrm{d}s\geq \frac{\lambda\overline{\theta}}{1+\varepsilon}$. Since this is true for all $\varepsilon>0$, this, together with the lim sup above, proves our theorem.

er queue; IID case

 We now specialize our analysis to a situation in which the workloads and inter-arrival times are IID. Letting $\tau_e = t_s - t_{s-t}$ be the time gap before the π^{ts} job arrives, this situation requires the $\{S_s\}$ and $\{\tau_a\}$ to be IID. There is, once again, only one server. We often denote this situation GI/GI/1

We also denote by w, the time that the nth job has to wait in queue before it is served. In that respect, $d_a = t_a + w_a + S_a$. Now, consider that $w_{n+1} = \begin{cases} 0 & d_a \leq t_{n+1} = (d_n - t_{n+1})^+ \\ d_n - t_{n+1} & d_n > t_{n+1} \end{cases}$. As such

 $\boxed{w_{n+1} = \left(w_n + S_* - \tau_{n+1}\right)^* \text{ Let } Z_* = S_{*-1} - \tau_n, \text{ We then have } w_{*+1} = \left(w_n + Z_{n+1}\right)^* = \max\left(0, w_n + Z_{n+1}\right)$ Since the Z_t are IID random variables, this is a random walk "capped off" at the origin. Letting Generally, $w_{\perp} = \sigma_{\perp} - \min_{t \in \mathbb{R}_+} \sigma_{\perp}$. The second term takes into account the reflected random walk, to

- One thing the GI/GI/1 framework gives us over the G/G/1 framework is that we can now say something more about the distribution of the $w_{_{n}}=\sigma_{_{n}}-\min_{0\leq n}\sigma_{_{\lambda}}=\max_{0\leq k\leq n}\{\sigma_{_{n}}-\sigma_{_{k}}\}=\max_{0\leq k\leq n}\{\sum_{k=k+1}^{n}Z_{_{k}}\}.\text{ Since IID, we can change indices on }$ the Z and $=_i \max_{0 \le k \le \pi} \{\sum_{j=1}^k Z_j\} = \max_{0 \le k \le \pi} \{\sigma_k\} = M_{\pi}$. Since M_{π} is a non-decreasing sequence, $M_{_0} \rightarrow_{_{ab}} M_{_{ci}} = \max_{b \ge 0} \sigma_{_b}. \text{ As such, } w_{_0} \Rightarrow M_{_{ci}} \text{ as } n \rightarrow \infty. \text{ [Note: convergence in distribution is the convergence of the distribution of the convergence of the con$ best we can hope for in this case, because M_a has some structure (the fact it's non-decreasing) that w_a does not. However, since this is a Markov chain, a stationary distribution is all we could really want
- o. If the random walk has positive drift in other words, if $\mathbb{E}(Z_s) = \mathbb{E}(S_{s-1}) \mathbb{E}(\tau_s) > 0$ then the random walk drifts to infinity and the waiting times get infinitely large. This is consistent with our findings in the G/G/1 queue, since $\mathbb{E}(\tau_{-,+}) > \mathbb{E}(S_+) \Leftrightarrow \rho < 1$. On the other hand, if the random walk has negative drift, the chain is stable and the waiting times return to 0 infinitely often almost surely (we motivated this result in homework 2 using a simpler reflected random walk).

 \circ We now consider the most tractable of all single-server queue models; the M/M/1 in queue. In that se, we assume the $\{S_n\}$ are IID and exponentially distributed with parameter μ whereas the $\{\tau_n\}$ are IID and exponentially distributed with parameter λ

 $X_{\mathbb{Z}/n}^+ \to_{n \to \infty} X_{\mathbb{Z}} \text{ with } \mathbb{E} \Big| X_{\mathbb{Z}} \Big| < \infty. \text{ Finally, consider } \mathbb{E} \Big[\|X_{\mathbb{Z}/n}\|_{\mathbb{Z}_{\mathbb{Z}/n}^{-\log}} \Big]. \text{ Simply split it over } \mathbb{I}_{\mathbb{Z}_{\geq n}} \text{ and } \mathbb{I}_{\mathbb{Z}>n} \text{ , drop } \mathbb{E} \Big[\|X_{\mathbb{Z}/n}\|_{\mathbb{Z}_{\mathbb{Z}/n}^{-\log}} \Big].$ hese indicators and use integrability of X_T and u.i. of $\{X_n\}$.

Example: Consider a gambler's ruin with wealth S_i at time t with $S_i = t$ and with probably $\forall s$ of going each direction at each time step. Let $t = P(P(\text{bolability we hit } N > t_i$ at which point we stop) And let 1 - p = P(P(bolability we hit 0, at which point we're ruined) $T=\inf\{n:S_n=N \text{ or } S_n=0\} \text{ We can now use the OST } \overline{|\text{On } S_i|} \text{ OST says that } \mathbb{E}(S_T)=\mathbb{E}(S_0)=i. \text{ Logical Polymer}$

 $\text{says} \quad \text{that} \quad \mathbb{B}(S_\tau) = pN + 0 \;. \quad \text{Together}, \quad \text{we} \quad \text{obtain} \quad p = i/N \cdot \frac{[\text{On } S_i^N - n]}{N} \quad \text{OST} \quad \text{says} \quad \text{that} \quad \mathbb{B}(S_\tau^N) = i^N, \quad \text{and} \quad \text{so} \quad \mathbb{B}(T) = \mathbb{E}(S_\tau^N) - i^N. \quad \text{Logic says} \quad \text{that} \quad \mathbb{E}(S_\tau^N) = pN^2 + 0. \quad \text{Together}, \quad \mathbb{E}(S_\tau^N) = i^N + 0. \quad \mathbb{E}(S_\tau^N) = i^N + 0.$ $\mathbb{E}(T) = i(N - i).$

- $\textbf{\textit{Counterexample:}} \ \, \text{Consider the example above, but with} \ \, T' = \inf \left\{ n : S_n = N > i \right\}. \ \, \text{This is well defined, in}$ that $\mathbb{P}(T' < \infty) = 1$ (because the random walk is an irreducible Markov chain, which means every state will eventually be visited) but blindly applying the OST gives $\mathbb{E}(S_{rr}) = i$, which implies that N = i. Clearly something has gone away. $\dots \textbf{Theorem:} \text{ If } T \leq n_t \text{ a.s. then } \mathbb{B}[X_T] = \mathbb{B}[X_{n_t}] \text{ . } \textbf{Proof:} \text{ } \mathbb{B}[X_T] = \mathbb{E}[X_{T^{-n_t}}] = \mathbb{E}[X_{b}]$
- Optional stopping: $\mathbb{E}[X_0] \stackrel{\text{(3)}}{=} \lim_{\pi} \mathbb{E}[X_{\Gamma \upharpoonright \pi}] \stackrel{\text{(2)}}{=} \mathbb{E}[\lim_{\pi} X_{\Gamma \upharpoonright \pi}] \stackrel{\text{(3)}}{=} \mathbb{E}[X_{\Gamma}]$ [u.i. ok for eg]
- Theorem: E||X_{*+1} − X_{*}|| |F_{*}| ≤ C < ∞ for n ⊆ T and E(T) < ∞ is enough.
 Example (Wald's Identity): Let {X_i} be IID with E||X_i| < ∞ and E(X_i) = µ. Let T be a stopping time with $\mathbb{B}(T)<\infty$. Then $\mathbb{E}(S_T)=\mathbb{E}(T)\mathbb{E}(X_1)$. **Proof.** Consider $\left\{S_n-n\mu\right\}$. Applying the OST gives the required result, given that $\mathbb{E}(|S_s - S_{s,s}| | \mathcal{F}_s) = \mathbb{E}|X_s| < \infty$.
- $T=\inf\{n:S_a=-a \text{ or } b\}. \text{ We would like to find } p_b=\mathbb{P}(S_q=b). \text{ (1) Try the exponential martingale } \rho^S$ (where $\rho = \frac{1-\mu}{r}$). Note that $0 \le M_{n \times T} = \rho^{\beta_{n \times T}} \le \rho^{n + b} \vee 1$; it is therefore bounded, and we can apply the OST to deduce that $1=\mathbb{E}(\rho^r)=\mathbb{E}(\rho^T)$. Also, $\mathbb{E}(\rho^T)=\rho^sp_++\rho^s(1-p_s)$. This allows us to find p_s (2) Now use the mean martingale $\left\{S_s-n(p-q)\right\}$. OST gives $\mathbb{E}[S_T-T(p-q)]=0\Rightarrow \mathbb{E}(S_T)=(p-q)\mathbb{E}(T)$. Using p_s , we can work out $\mathbb{E}(S_{-})$ and find $\mathbb{E}(T)$.
- Note that the OST does not necessarily require P(T < ∞) − 1. Indeed, E(X_T) = E(X_TI_{Tem} + X_TI_{Tem}), and if the stopped martingale is u.i., X_{\bowtie} must exist.
- . It is important to remember that when we invoke the martingale convergence theorem so say that X_- , we are implicitly implying that $P(T < \infty) = 1$

Martingale Inequalities

- - $\circ \quad \pmb{Motivation:} \text{ Markov's Inequality states that } a \mathbb{P} \left(\! \left| X \right| > a \right) \leq \mathbb{E} \left| X \right|.$
 - $\circ \quad \textbf{Theorem:} \text{ If } \left\{ X_a \right\} \text{ is a submartingale and } A = \left\{ \max_{0 \leq i \leq a} X_i \geq a \right\}, \text{ then } a \mathbb{P}(A) \leq \mathbb{E}[X_a \mathbb{I}_A] \leq \mathbb{E}[X_a^*]$

 $s \to -\infty$, the LHS above is such a subsequence. Thus, letting $s \to -\infty$, we find $1 \leq \frac{\sum_{i \in \mathcal{I}} \beta_i |_{[\rho \in \mathcal{Q}, r]}}{\dots p} \to_{i \to -\infty} \rho$

Proposition: If ρ < 1, then coupling time T_e < ∞ a.s.

Proof. WLOG, assume $\tau = 0$ and denote $W^{\alpha}_{rt} \equiv W^{\alpha}_{t}$ [work in system at t given started at 0 with α Assume that $\alpha > X^*(\omega)$. Then $T_s = \inf\{t > 0 : W^{\alpha}_t = 0\}$. Assume $\rho < 1$ and suppose $T_n = \infty$ on a set of nonzero probability. This implies that $W_i^* > 0 \ \forall t \geq 0$ and that the server is constantly working

we obtain $1 \le \frac{\alpha}{1} + \frac{\sum_{s \in S} \delta_s b_{b_s \oplus s, \frac{1}{2}}}{1} \rightarrow_{t \to c_s} \rho$. Contradiction.

 $Proposition: \text{If } \rho < 1 \text{ } \sup_{A_i, \cdots, A_t} \left| \mathbb{P} \left\{ W^*_{i, +} \in A_i, \cdots, W^*_{i, +}, \in A_t \right\} - \mathbb{P} \left\{ X^*_{i_i} \in A_i, \cdots, X^*_{i_t} \in A_j \right\} \right| \rightarrow_{-\infty} 0$ Where $A_{\gamma},\cdots,A_{\epsilon}$ are measurable sets and for all $(t_{\gamma},\cdots,t_{\kappa})\in\mathbb{R}^{n}$ and $\alpha>0$. This is called *convergence* is total variation and is stronger than weak convergence

 We can compare to what happens in Markov chains. Consider a finite-state, irreducible Markov $\text{chain, \& consider } \left| \mathbb{P}\left\{X_n = i \mid X_0 = j\right\} - \mathbb{P}_*\left\{X_n = i\right\} \right| \leq \max_{i,j} \mathbb{P}_j\left\{T_i > n\right\} \leq \left(\max_{i,j} \mathbb{E}_j e^{\theta_i^*}\right) e^{-\theta n}$

o **Proposition**: If $\rho > 1$, then for all $\alpha > 0$, $\liminf_{r \to \infty} \frac{k_r^{\alpha}}{r} > 0$ almost surely. In other words, the ${\it Proof.}$ Denote the cumulative idle time up to time t as I_t . We then have $W^s_t = \alpha + \sum_{e \in \mathbb{Z}} S_s \mathbf{1}_{\{i_e \in \mathbb{N}\}} - \left(t - I_r\right) \geq \sum_{e \in \mathbb{Z}} S_s \mathbf{1}_{\{i_e \in \mathbb{N}\}} - t \text{. Dividing by } t \xrightarrow{\mathbb{S}^s_t} \geq \frac{\sum_{e \in \mathbb{Z}} \mathbb{S}^s_{\{i_e \in \mathbb{N}\}} - 1}{t} - 1 \text{. Letting}$ $t \to \infty$, we get that $\liminf_{t \to \infty} \frac{\mathcal{B}_t^n}{t} \ge \rho - 1 > 0$.

 Proposition: Busy probability of an arbitrary server is ρ. Proposition: By Little's Law, ρ is also the expected number of customers in service [arrival λ , sojourn \pm]

• Little's Law (Conservation Laws)

• We now consider a setting in which work $(t_n, S_n : n \in \mathbb{Z})$ enters a system and then leaves the system at a time $(d: n \in \mathbb{Z})$. We let θ be the sojourn time of the n^{th} job in the system, given by d-tWe define the following quantities $A(t) = \sup \left\{ n : t_{_0} \le t \right\} = \text{number of arrivals in } [0,t]$ and D(t) = number of of departures in [0,t] and N(t) = A(t) - D(t) = work in the system at time tThe only two assumptions we make is that the following are true for every sample path (1) $\lim_{t \to \infty} \frac{A(t)}{t} = \lambda \in (0,\infty) \ (2) \ \lim_{t \to \infty} \frac{\sum_{k=1}^{t} \theta_{k}}{t} = \overline{\theta} \in (0,\infty)$

• Proposition: Under these assumptions, $\frac{1}{4} \int_{0}^{t} N(s) ds \rightarrow \lambda \overline{\theta}$

o Consider the process X(t) = Number of jobs in system at time $t \ge 0$ $\{X(t): t \ge 0\}$ is CTM6

$$\mathbb{P}\left\{X(t+h)=j\mid X(t)=i\right\} = \begin{cases} \lambda h + o(h) & j=j+1\\ \mu h + o(h) & j=j-1\\ 1-(\lambda+\mu)h + o(h) & j=i\\ o(h) & \text{otherwise} \end{cases}$$

Our transition matrix P then takes the form (rows sum to 1)

$$P_{\lambda} = I + \begin{vmatrix} -\lambda & \lambda & 0 \\ \mu & -(\lambda + \mu) & \lambda & 0 \\ 0 & \mu & -(\lambda + \mu) & \lambda & 0 \\ 0 & \mu & \ddots & \ddots \\ 0 & 0 & \ddots & \ddots \\ P_{\lambda} = I + Qh + o(h) \end{vmatrix} + h + o(h)$$

Q is the rate matrix, defined by $Q=\lim_{i\downarrow 0} \frac{t_i-t}{b}$. The steady-state equations in this case are $\pi^{\top}P_{b} = \pi^{\top}, \ \pi \geq 0, \ \pi \cdot c = 1.$ Feeding our expression for P_{b} into the first equation, we obtain $\pi^{\top} + \pi^{\top}Qh + o(h) = \pi^{\top} \Rightarrow \pi^{\top}Q = 0$. For our particular matrix, this give $-\lambda \pi_s + \mu \pi_s = 0$ and $\lambda \pi_{_{q-1}} + (\mu + \lambda) \pi_{_n} + \mu \pi_{_{q+1}} = 0. \ \ \text{Letting} \ \ \rho = \lambda \, / \, \mu \ \ \text{and assuming} \ \ \rho < 1, \ \text{we obtain} \ \ \pi_0 \rho = \pi_{_1} \ \ \text{and}$
$$\begin{split} & \rho \pi_{n+1} - (1+\rho)\pi_n + \pi_{n+1} = 0 \,. \quad \text{Solving this recurrence relation, we obtain } \pi_e = c \rho^e \quad \text{and} \\ & \sum \pi_e = 1 \Rightarrow c = 1 - \rho \,. \\ & \text{Solv} \quad \frac{\pi_e - (1-\rho) \rho^e}{n} \qquad n \geq 0 \end{split}$$
 This expression passes a "sunity check" at n= 0; the probability the chain is empty is given by $\pi_0 = 1 - \rho = 1 - \frac{1}{\rho}$, which we would expect to be the average amount of time the system is empty

 $_{\odot}$. We can use Little's Law to good effect; consider the following two examples; the first is trivial, the

Let S be the number of items in the server. The average sojourn time in the server is $\frac{1}{2}$. As such, by Little's Law $\mathbb{E}_s(S) = \frac{\lambda}{s} = \rho$. Note, however, that $S = 1 \cdot \mathbb{1}_{r_{\text{joins in bary}}} + 0 \cdot \mathbb{1}_{r_{\text{join}}}$ As such, $\mathbb{E}_{\gamma}(S) = \mathbb{P}(System \text{ is busy}) = \rho$. The result above is therefore consistent with what we would expect.

■ Consider the queue as the "system"

Let Q be the number of items in the queue. The sojourn time in the queue is simply the waiting time, w_r . As such, by Little's Law. $\mathbb{E}_{_{\mathbb{F}}}(Q) = \lambda \mathbb{E}_{_{\mathbb{F}}}(w)$ (where w is the waiting time for any new item that joins the queue). Now, note that $Q(t) = (X(t) - 1)^+$ (we subtract item currently in the server). Thus $E_s(Q) = \sum_{i=1}^n (n-1)(1-\rho)\rho^i = \frac{s^i}{1-\rho}$. Thus $\rho / \mu(1-\rho)$

 We know consider the more difficult problem of deriving the probability distribution of waiting times $\mathbb{P}_{_{\mathbb{Z}}}(w>x).$ Once again, recall w is the wait time experienced by a random job entering the queue.

o If we let $S_a = 0$ and $S_a = \sum_{i=1}^n X_i$ were the X_a are IID with $\mathbb{E}[X_a] = 0$, $\text{Var}[X_a] = \sigma^2$, then $\{S_a\}$ is a martingale, and $\{K_i\} = \{S_i^i\}$ is a submartingale. As such, we get Kolmogorov's Inequality.

$$\mathbb{P}\left(\max\nolimits_{0\leq k\leq n}\left\|S_{k}\right\|\geq x\right)=\mathbb{P}\left(\max\nolimits_{0\leq k\leq n}X_{i_{k}}\geq x^{2}\right)\leq \frac{\mathbb{E}[S_{i_{k}}^{2}]}{x}=\frac{n\sigma^{2}}{x^{2}}$$

o Theorem (Azuma's Inequality): Let $\left\{Z_{e}\right\}$ be a zero-mean martingale with bounded MG differences (ie: $-\alpha \le Z_i - Z_{i-1} \le \beta$ for $\alpha, \beta \ge 0$). Then

$$\mathbb{P}\left(\bigcup\nolimits_{n=m}^{\infty} \! \left| Z_{n} \right| > n\varepsilon\right) \! \leq 2 \exp \! \left(\! - \frac{2m\varepsilon^{2}}{(\alpha + \beta)^{2}} \! \right)$$

This bound is not as tight as the CLT's, but it requires less

o Definition (Doob Martingale): Let X be a random variable in L_1 and \mathcal{F}_a be a set of filtrations Then $X_n = \mathbb{E}(X \mid \mathcal{F}_n)$ is a martingale

Proof.
$$\mathbb{E}(X_{n+1} | \mathcal{F}_n) = \mathbb{E}[\mathbb{E}(X | \mathcal{F}_{n+1}) | \mathcal{F}_n] = \mathbb{E}(X | \mathcal{F}_n) = X_n$$
.

o Let $X = (X_1, \dots, X_n)$, where the X_i are independent and with CDF F_r Define $\mathcal{F}_i = \sigma(X_1, \dots, X_i)$. Finally, let $h: \mathbb{R}^t \to \mathbb{R}$ such that, if x differs from y in only one component, $|h(x) - h(y)| \le \ell$, for some $t \ge 0$. Then $S_i = \mathbb{E}[h(X) \mid \mathcal{F}_i]$ is a Doob martingale. Provided we can prove $|S_i - S_{i,i}| \le t$, we can apply Azuma's Inequality with $\alpha + \beta = \ell$ to $S_n = h(X) \mathbb{P}\left[h(X) - \mathbb{E}\left[h(X)\right] > n\varepsilon\right] \le 2 \exp\left[-\frac{n\varepsilon^2}{2\ell^2}\right]$

Martingale Convergence

 Theorem: If {X_∗} is a submartingale and sup_n E|X_n| < ∞ (this is a weaker condition than u.i.), then $x^+ \leq |x| = 2x^+ - x \text{ , and so, for example, } \mathbb{E}[X_a^-] = 2\mathbb{E}[X_a^+] - \mathbb{E}[X_a^-] \leq 2\mathbb{E}[X_a^+] - \mathbb{E}[X_0] \text{ .}$

Proof. Note that $(X_n - a)^+ \le X_n^+ + |a|$ and write the upcrossing inequality as $\mathbb{E}[U_n] \le \frac{\mathbb{E}[X_n^+] + |a|}{1 - a} = K < \infty$ [using the fact |X| dominates X' and the condition in the theorem). However, U_c is increasing by definition and therefore tends to some U [possibly ∞], but by monotone convergence, $\mathbb{E}(U_c) \to \mathbb{E}(U) < \infty$. Thus, the number of up-crossings must be finite, and so $\mathbb{P}(\liminf X_c < a < b < \limsup N_c) = 0$. This is true for any aand b, and so P(lim inf X = lim sup X) = 1. Integrability of the limit follows by Fatou.

■

 Corollary If {X_s} is a supermattingale and X_s ≥ 0, then X_s → X and ∑|X| ≤ ∑|X_s|.
 Proof. Let Y_s = -X_s − this is a submattingale with ∑|Y_s | = 0. The condition of the theorem above (see the remark) is therefore satisfied. Note, however, that almost sure converge does not imply convergence in

the remain j is therefore saturates. Assume a contrapt with the contrapt was a non-imply convergence in the measure of variance, as the next two examples illustrates.

Example: Assume $X_j = i > 0$, and $X_{i,j} \mid X_{i-1} \sim \text{Po}(X_{i-j})$. Clearly, this is a martingale, and once we hit 0, we stay there. Let $T = \inf\{n : X_i = 0 \text{ or } X_i \ge b\}$. By optional stopping, $E(X_T) = b(1-p)$, where $b \ge b$ and $p = \mathbb{P}(X_y = 0). \text{ But } \mathbb{E}(X_y) = i. \text{ As such, } 1 - p \to \frac{1}{2} \to 0 \text{ as } b \to \infty. \text{ Thus, } p \to 1. \text{ How do we know stopping time is finite?} \\ \text{Stop, however, that } \mathbb{E}[X_y^2] = \mathbb{E}[\mathbb{E}[X_y^2] \mid X_{i-1}]) = \mathbb{E}(X_{i-1}^2) + i. \text{ As such, } \mathbb{V}\text{ar}(X_s) = ni: \text{ the variable itself tends to 0, but the variance blows up.} \\ \square$

 $\textbf{\textit{Proof:}} \quad \int_{4}^{t} N(s) \; \mathrm{d}s = \int_{0}^{t} A(s) - D(s) \; \mathrm{d}s \; . \; \text{We can write} \quad A(s) = \sum_{s \in \mathbb{Z}} \mathbb{1}_{[t_s, t_s]} \quad \text{and} \quad D(s) = \sum_{s \in \mathbb{Z}} \mathbb{1}_{[t_s, t_s]} \cdot \mathbb$ As such $N(s) = \sum_{s \in \mathbb{Z}} \mathbf{1}_{[i_s > s]} - \mathbf{1}_{[i_s > s]} = \sum_{s \in \mathbb{Z}} \mathbf{1}_{[i_s > s < s]}$ (The last equality follows because any jobs that arrive after s won't be counted at all, and any events that arrive and leave before s will be counted by both indicators and therefore cancel out). Swapping the summation and integration (Fubini)

$$\int_0^t N(s) \; \mathrm{d} s \; = \sum\nolimits_{s \in \mathbb{Z}} \int_0^t \mathbf{1}_{\{t_s \leq r \leq t_s\}} \; \mathrm{d} s = \sum\nolimits_{s \in \mathbb{Z}} \left\{ \underset{\text{in the system during } [0,t]}{\operatorname{Amount of time job} \; n \; \text{was}} \right\}$$

We can bound this above by considering the sojourn time of all arrivals up to and including time t (though some of them may overrun past t) and lower bound it by considering the sojourn time of all job that depart before time t (even though some jobs that leave after t do spend some time in the system before t). This gives $\sum_{i=0}^{D(t)} \theta_{n_i} \le \int_0^t N(s) ds \le \sum_{s=0}^{A(t)} \theta_{n_i}$. Where n_i is the index of the t^{h_i} job to umed FIFO processing discipline, we cannot assume that leave the system (since we have no ass $\theta_i = i$). Before we continue, we will need the following claim

Claim: Under the two assumptions above
$$\theta_{i}$$
 / t_{i} - t_{i}

Now by our claim, for all $\varepsilon > 0$, there exists an $N(\varepsilon)$ such that for $n > N(\varepsilon) \frac{\delta_{\varepsilon}}{t} \le \varepsilon \Rightarrow \frac{\delta_{\varepsilon} - t_{\varepsilon}}{t} \le \varepsilon$. This implies that $d_{\omega} \leq (1 + \varepsilon)t_{\omega} \forall n > N(\varepsilon)$. This means that all jobs after the $N(\varepsilon)$ th job that arrive in [0, 1, 1]t[will have departed by time $t(1+\varepsilon)$. Therefore $\sum_{n=N(\varepsilon)+1}^{A(\varepsilon)} \theta_n \le \sum_{i=0}^{D(0)+i[)} \theta_n$. Putting this together with the bounds developed above, we find that

$$\frac{1}{t(1+\varepsilon)} \sum\nolimits_{e=N(\varepsilon)+1}^{d(t)} \theta_e \leq \frac{1}{t(1+\varepsilon)} \int_0^{t(t+\varepsilon)} N(s) \ \mathrm{d}s \leq \frac{1}{t(1+\varepsilon)} \sum\nolimits_{n=1}^{d(N(t+\varepsilon))} \theta_e$$

Let's first consider the upper bound

$$\frac{1}{t(1+\varepsilon)} \sum\nolimits_{i=1}^{s(t(1+\varepsilon))} \theta_{a} = \left| \frac{A \left(t(1+\varepsilon) \right)}{t(1+\varepsilon)} \right| \left| \frac{1}{A \left(t(1+\varepsilon) \right)} \sum\nolimits_{i=1}^{s(t(1+\varepsilon))} \theta_{a} \right| \rightarrow \lambda \overline{\theta}$$

The first term tends to λ , by assumption 1. The second term tends to $\overline{\theta}$ because (1) By assumption 1, $A(t) \rightarrow_{t \rightarrow \infty} \infty$ (2) By assumption 2, $\frac{\sum \theta_t}{t} \rightarrow \overline{\theta}$, which means any subsequence thereof also $\rightarrow \overline{\theta}$ Since $A(t(1+\varepsilon)) \to \infty$, the second term above is precisely such a subsequence. This implies that

$$\begin{aligned} & \limsup_{\epsilon \to 0} \frac{1}{t} \int_{0}^{t} N(\epsilon) \, d\epsilon \leq \lambda \overline{\theta}. & \text{Now the lower} & \text{bound} & \frac{1}{t(1+\epsilon)} \sum_{\alpha = 0 \leq (i+1)}^{A(i)} \theta_{\alpha} \\ & = \frac{1}{t} \frac{A(t)}{t} \frac{1}{1+\epsilon} \sum_{k = 0 \leq (i+1)}^{A(i)} \theta_{\epsilon} = \frac{1}{1+\epsilon} \frac{A(t)}{t} \sum_{\alpha = 0}^{A(i)} \theta_{\epsilon} - \sum_{\alpha = 0}^{N(i)} \theta_{\epsilon} \\ & = \frac{1}{t} \frac{A(t)}{t} \frac{1}{1+\epsilon} \sum_{k = 0 \leq (i+1)}^{A(i)} \theta_{\epsilon} = \frac{1}{t} \frac{A(t)}{t} \sum_{\alpha = 0}^{A(i)} \theta_{\epsilon} - \sum_{\alpha = 0}^{N(i)} \theta_{\epsilon} \\ & = \frac{1}{t} \frac{A(t)}{t} \frac{1}{1+\epsilon} \sum_{\alpha = 0 \leq (i+1)}^{A(i)} \theta_{\epsilon} \end{aligned}$$

$$\begin{split} \mathbb{P}_{\boldsymbol{q}}\left(\boldsymbol{w}>\boldsymbol{x}\right) &= 0 \cdot \mathbb{P}\left(\boldsymbol{X}=\boldsymbol{0}\right) + \sum_{k=1}^{n} \mathbb{P}_{\boldsymbol{x}}\left(\boldsymbol{w}>\boldsymbol{x} \mid \boldsymbol{X}=\boldsymbol{k}\right) \mathbb{P}_{\boldsymbol{q}}\left(\boldsymbol{X}=\boldsymbol{k}\right) \\ &= \sum_{k=1}^{n} \mathbb{P}_{\boldsymbol{q}}\left(\boldsymbol{w}>\boldsymbol{x} \mid \boldsymbol{X}=\boldsymbol{k}\right) (1-\rho) \rho^{\delta} \end{split}$$

Now, note that since the exponential distribution is memoryless, we can write

$$(w \mid X = k) = \underbrace{ \begin{array}{c} \text{Fanolizing Wine} \\ \text{fit job extractly} \\ \text{fit is} \\ \text{fit job extractly} \\ \text{fit is} \\ \text{fit is}$$

(the Erlang distribution is the distribution of the sum of exponential variables; it is a special case of the Gamma distribution). As such

$$\begin{split} f_{\varepsilon}(z) &= \sum_{i=1}^{n_{\varepsilon}} \frac{e^{-i\omega_{i}\rho_{i}^{-1}\beta_{i}}}{(n+\beta)^{2}} \rho^{3}(1-\rho) = e^{-i\omega}\mu(1-\rho)\rho \sum_{k=1}^{n_{\varepsilon}} \frac{(i\omega^{k-1}}{(n+\beta)}\rho^{k-1} = \rho\mu(1-\rho)e^{-i\rho(1-\rho)z} \\ \text{And so } w - \begin{bmatrix} \exp\left(\rho(1-\rho)\right) & \text{with prob } \rho \\ 1-\rho & \text{and } \mathbb{P}\left(w>x\right) = \rho e^{-ix(i)-\rho z} \\ 1 - \rho & \text{otherwise} \end{bmatrix} \end{split}$$

Prop 6.11 (M/M/c queue). $\mu_n = n\mu$ if n < c and $c\mu$ otherwise. $\lambda_n = \lambda$. Then $P(L = n) = p_0 = p_0 \frac{\lambda^n}{n! dx^n}$ if n < c and $\begin{aligned} & p_{W} \frac{g^{\mu\nu}}{e^{\mu\nu}} & \textit{otherwise. Summing the probabilities to 1, } p_{0} = \left(\sum_{n=0}^{n-1} \frac{e^{n}}{e^{n}} + \frac{e^{\mu\nu}}{e^{\mu\nu}}\right)^{-1} & \textit{where } e^{-\frac{1}{2}} & \textit{sind } \frac{e}{e} = p_{0} \frac{e^{\mu\nu}}{e^{\mu\nu}} + \frac{e^{\mu\nu}}{e^{\mu\nu}} & \textit{where } e^{-\frac{1}{2}} & \textit{what mod } e \in \mathbb{N}. \ \, \text{be taking time distribution is } e^{\mu}(\mathbf{u}_{p} \times \mathbf{u}) = \frac{e^{\mu\nu}}{e^{\mu\nu}} e^{\mu\nu} e^{\mu\nu} & \textit{When } \mathbf{u} > e \text{ the significant } \\ & \textit{single is Poisson with more ep and the distribution of the time for the <math>n = e^{+}$ to end to so e^{μ} for $e^{\mu\nu}$ is e^{μ} to $e^{\mu\nu}$ and e^{μ} is e^{μ} to e^{μ} and e^{μ} in e^{μ} to e^{μ} in e^{μ} Prop 6.12 (M/M/c/K quow). $\mu_n = \eta_1 \ \eta' u < \epsilon$ and $\varrho_1 \ n \ w$ $\lambda_n = \lambda_1 \eta < K$ and $0 \ n w$ $Dnn P(L = n) = \mu_n = \mu_0 \frac{\lambda_1 u}{2\pi}$ $\eta' u < \epsilon$ and $\eta = \frac{\lambda_1 u}{2\pi} \frac{\eta' u}{2\pi} \le K$. Since a fraction $\eta_2 v$ of varieth δu and $\beta u in the system, <math>b_1 the P(EE)$ property of different variant at the exempt $b = secret n V(L = \mu_0) = \frac{\lambda_1 u}{2\pi} \frac{1}{2\pi} \frac{1}{$

Prop 6.12. Consider a M/M/I/K queue. Then, $q_n = \frac{p_n}{1-p_K}$, i.e.s PASTA does not hold.

Prop 6.14 (M/M/ ∞ queue), $\mu_0 = n\mu$ and $\lambda_0 = \lambda$. Then $P(L = n) \equiv \rho_0 - \rho_0 \frac{n}{n!}$ where $\rho_0 = e^{-r}$ and $r = \frac{\lambda}{\mu}$ (also called for M/G/ ∞). Steady state solution exists $\forall \rho$. L = r.

Prop 6.15 (Finite source spaces), $\mu_0 = u_0$ if $n < and c \mu$ o.s. $\lambda_0 = (M - n)\lambda$ if n < M and 0 o.s. Then $P(L = n) \equiv p_0 = p_0^{-1} \frac{1}{2m_0^2 - m_0^2}$ and $p_0 = p_0^{-1} \frac{1}{2m_0^2 - m_$

Def 6.16 (Busy period). A basy cycle is the sum of the basy period and the idle period. For all M/G/I type of where $E(T_{kp}) = \frac{1}{\mu-\lambda}$ and $E(T_{kc}) = \frac{1}{\lambda} + \frac{1}{\mu-\lambda}$.

- Also require R(t). To sidestep this complication, we will consider the following embedded Markov chain X_π . Let T_π be the time at which the n^{th} job concludes processing, and denote $X(T_{s^k}) = X_{s} = \frac{\text{Number of jobs in the system}}{\text{immediately after the } n^{t_k} \text{ job as departed}}. \text{ We then have } X_{s+1} = \left(X_{s} - 1\right)^{s} + A_{s+1}.$ where $A_{n,+}$, is the number of arrivals during the processing time of the (n+1)th job. In this case, by
- sumption, the A_n are IID, and $(A_n | S_n = s) Po(\lambda s)$, where λ is the rate of arrivals o Now, using the ergodic theorem for DTMCs (and assuming we have stability; ie: $\rho < 1$), we have $\mathbb{P}(X_s = j) \rightarrow_{n \rightarrow \infty} \pi(j)$. Furthermore, from the G/G/1 case, we know that for each sample path

 $X(t) = X_i^* \text{ exists, which implies that } \mathbb{P}\left(X(t) = j\right) \to_{i \to \infty} \hat{\pi}(j). \text{ The challenge now, however, is to prove the exists of th$

o – The PK formula $\mathbb{E}_{\pi}(w) = \frac{1 + \frac{\sigma_{\pi}^{1}}{\rho_{\pi}^{1}}}{2} \cdot \frac{\rho}{1 - \rho} \cdot \mathbb{E}(S)$.

Def 6.20 (Departure Point Stordy Scales). Let the inholded Markov chain at the departure points be $\mathbf{P} = [p_{ij}]$ $p_{ij} = P(X_{i+1} = j|X_{i} = r) = \int_{0}^{\infty} \frac{e^{-i\chi_{i}(j_{i})-r+1}}{e^{-i\chi_{i}(j_{i})-r+1}} e^{-i\chi_{i}} \int_{0}^{\infty} \frac{e^{-i\chi_{i}(j_{i})-r+1}}{e^{-i\chi_{i}(j_{i})-r+1}} e^{-i\chi_{i}} \int_{0}^{\infty} \frac{e^{-i\chi_{i}(j_{i})-r+1}}{e^{-i\chi_{i}(j_{i})-r+1}} e^{-i\chi_{i}} \int_{0}^{\infty} \frac{e^{-i\chi_{i}(j_{i})-r+1}}{e^{-i\chi_{i}(j_{i})-r+1}} e^{-i\chi_{i}} \int_{0}^{\infty} \frac{e^{-i\chi_{i}(j_{i})-r+1}}{e^{-i\chi_{i}(j_{i})-r+1}} e^{-i\chi_{i}(j_{i})-r+1}} \int_{0}^{\infty} \frac{e^{-i\chi_{i}(j_{i})-r+1}}{e^{-i\chi_{i}(j_{i})-r+1}} e^{-i\chi_{i}(j_{i})-r+1}} \int_{0}^{\infty} \frac{e^{-i\chi_{i}(j_{i})-r+1}}{e^{-i\chi_{i}(j_{i})-r+1}} e^{-i\chi_{i}(j_{i})-r+1}} e^{-i\chi$

Thm 6.21 (Erlang loss formula (M/G/k/k) (valid for M/M/k/k). The limiting distribution of the number of customers in the system is $P(n) = \frac{P(kS)^{-1}}{\sum_{k} M(kS)^{2}/k}$, and given that there are n in the system, the residual times are iid with the equilibrium distribution of G, given by $G_{C}(x) = \frac{K}{2S} (S(x))$

Addendum on PASTA

o The principle of PASTA (Poisson Arrivals see Time Averages) states that for any stochastic process X(t) over a state space S, and for any $A \subseteq S$

$$\lim_{\epsilon \to \infty} \frac{1}{n} \sum_{t=1}^{\epsilon} \mathbf{1}_{\{X(t) \ge \delta\}} = \lim_{t \to \infty} \frac{1}{t} \int_{0}^{t} \mathbf{1}_{\{X(t) \ge \delta\}} \ \mathrm{d}s$$
 provided the t_k form a Poisson process – in other words, $t_k - t_{k-1} - \exp(\lambda t)$

6.6 G/M/1: General input and exponential service

The space of the space pass depth and exponentials servine the number in the space that the ith arrival sees upon pinning the space no. Thus, $N_{B_1} = (N_{B_1} + D_0)^{\frac{1}{2}}$ where $D_0 = 0$ is number of numbers around during the interaction that the space of the space of

Renewal & Regenerative Process

- Let $\{X_n\}$ be IID, with $\mathbb{E}(X_n) = \mu < \infty$ and $\mathbb{P}(X_n = 0) < 1$. Let $S_n = \sum_{i=1}^n X_i$, with $S_0 = 0$. Let $N(t) = \sup \left\{ n \geq 1 : S_n \leq t \right\}.$ $\left\{ N(t) : t \geq 0 \right\}$ is called a renewal process
- **Definition** (renewal function): The renewal function is defined as $m(t) = \mathbb{E}[N(t)]$
- o Example: Let $X_t = \exp(1/\mu)$. $\{N(t): t \ge 0\}$ is then a Poisson process. Consider, incidentally, that in a Poisson process, the following two facts are true. Much of our work in this section will be concerned with generalizing these results to general renewal processes:
 - E(N(t)) = m(t) = μt = E(X)t (generalizes to the cicentary renewal theorem)

■ This is an equation of the form above, the solution of which is $P(t) = \overline{H}(t) + \int_{0}^{t} \overline{H}(t-s) dm_{p}(s)$. We now find $\lim_{t\to\infty} P(t)$. To do this, we note that $\overline{H}(\infty)=0$, and that, by the key renewal theorem, $m_p'(s)\approx 1\,/\,\mu_p$. Thus

$$\lim_{t \to \infty} P(t) = \frac{\int_0^\infty \overline{H}(t-s) \; \mathrm{d}s}{\mathbb{E}(F)} = \frac{\mathbb{E}(^* \mathrm{On}^n \; \mathrm{time \; per \; cycle})}{\mathbb{E}(^* \mathrm{On}^n \; t. \; \mathrm{per \; c.}) + \mathbb{E}(^* \mathrm{Off}^n \; t. \; \mathrm{per \; c.})}$$

- o The Excess and the Age
 - We define the following three random variables (1) $\overline{A(t) = S_{N(t)+1} t}$ is the age at t the amount of time since the last renewal. (2) $\overline{Y(t) = t - S_{E(t)}}$ is the excess/residual life at t – the amount of time till the next renewal. (3) $\overline{L(t) = Y(t) + A(t) = S_{_{\mathcal{I}(t)+1}} - S_{_{\mathcal{I}(t)}}} \ \ \text{is the length of}$ the time interval between the two events flanking the time point t.

As usual, let X_i be the arrival time distributions. Use alternating ren

 Age: To find P(t) = P(A(t) ≤ x), let the cycle be "on" for the first x units of tim since its last renewal, and "off" thereafter. We then have

$$\lim_{t \to \infty} P(t) = \frac{\mathbb{E} \big(\text{Length of "on" time} \big)}{\mathbb{E} \big(\text{Length of cycle} \big)} = \frac{\mathbb{E} \big(\min[X,x] \big)}{\mu} = \frac{\int_{g}^{\infty} \mathbb{P} \big(\min[X,x] > y \big) \ \mathrm{d}y}{\mu} = \frac{\int_{g}^{s} \overline{F}(y) \ \mathrm{d}y}{\mathbb{E}(X)}$$

• Residual life: To find $P(t) = \mathbb{P}(Y(t) \le x)$, we consider a cycle to be "on" until the last z units of the renewal cycle. We then have

$$\lim\nolimits_{n\to\infty}P(t)=\frac{\mathbb{E}\!\left(\text{Length of "off" time}\right)}{\mathbb{E}\!\left(\text{Length of cycle}\right)}=\frac{\mathbb{E}\!\left(\min[X,x]\right)}{\mu}=\frac{\int_{z}^{\varepsilon}\overline{F}(y)\;\mathrm{d}y}{\mathbb{E}(X)}$$

- \circ In a renewal-reward process, a reward R_{γ} is earned at each renewal. The renewal-reward stochastic process is then given by $R(t) = \sum_{n=1}^{R(t)} R_n$. We may assume that R_n depends on X_n , the length of the n^{th} renewal interval. We assume, however, that the pairs (X_n, R_n) are IID.
- **Theorem:** With probability 1, $R(t)/t \to \mathbb{E}(R)/\mathbb{E}(X)$. Where X is the length of a cycle (ie: between renewals). This theorem simply states that the average long-term reward is the reward per cycle divided by the length of the cycle. **Proof.** We write $\frac{R(t)}{t} = \frac{\sum_{i=1}^{N(t)} R_a}{N(t)} \frac{N(t)}{t}$. By the strong law for R_a .

the first term tends to E(R). By the strong law for renewal processes, second term to 1 / E(X).

- - $\text{o} \quad \text{Let} \quad \mathbb{P} \left(X_{_{q}} = -1 \right) = \mathbb{E} \left(X_{_{q}} = 1 \right) = \tfrac{1}{2} \,, \text{ and let} \quad N = \min \left\{ n : X_{_{1}} + \dots + X_{_{N}} = 1 \right\} . \quad N \text{ is a stopping time}$ Wald's Equation leads a contradiction, and $\mathbb{E}(N) = \infty$

 - o Stationary increments if the distribution of events that occur in any interval of time depends only or length of interval. Eg, distribution of $N(t_2) - N(t_1)$ must be the same as that of $N(t_2 + s) - N(t_1 + s)$.

The Poisson Proces.

- $\circ\quad \textbf{Definition:} \ \text{A counting process} \ \left\{ N(t), t \geq 0 \right\} \ \text{is said to be a poisson process having rate} \ \lambda > 0 \ \text{if (1)}$ N(0) = 0 (2) The process has independent increments (3) $P(N(s+t) - N(s)) - Po(\lambda t)$. This automatically implies the process has stationary increments, and that $\mathbb{E}(N(t)) = \lambda t$.
- o Definition: A counting process $\{N(t), t \geq 0\}$ is said to be a poisson process having rate $\lambda > 0$ if (1) N(0) = 0 (2) The process has stationary and independent increments. (3) $\mathbb{P}(N(h) = 1) = \lambda h + o(h)$ (4) $\mathbb{P}(N(h) \ge 2) = o(h)$. Where, if we say f is o(h), we mean that $\lim_{t \to 0} f(h) / h = 0$.

- \circ Let X_1 be the time of the first event, and X_n be the time between the n^n and $(n-1)^{\alpha}$ events. (1) First, note that $\mathbb{P}(X_1>t)=\mathbb{P}(N(t)=0)=e^{-\lambda t}$ (2) Then, note that $\mathbb{P}\left(X_{s} > t \mid X_{1} = s\right) = \mathbb{P}\left(0 \text{ events in } (s, s + t \mid |X_{1} = s\right) =_{\text{tadip}} \mathbb{P}\left(0 \text{ events in } (s, s + t)\right) =_{\text{max}} e^{-it} \quad \text{Thus, } X_{2} = 0$ is also an exponential random variable, independent of X_1 .
- Now, consider the arrival time of the nth events, S_s = Σ⁰_{i=1} X_s. It can be shown that S_s ~ Γ(λ, n) in three ways: (1) Using moment generating functions. (2) Noting that $N(t) \geq n \Leftrightarrow S_n \leq t$, which implies that $\mathbb{P}\left(S_{\pi} \leq t\right) = \mathbb{P}\left(N(t) \geq n\right) = \sum_{j=s}^{\infty} e^{-it} \frac{(jsy)}{j!}$ Differentiating leads to f(t). (3) Using the independent increment assumptions $\mathbb{P}(S_{\omega} \in (t, t + dt)) = \mathbb{P}(N(t) = n - 1, N(dt) = 1) + o(dt)$
- $=\frac{e^{-3t}(\lambda t)^{n-1}}{(n-1)!}\lambda \mathrm{d}t + o(\mathrm{d}t) \ \mathrm{Which, \, letting} \ \mathrm{d}t \to 0 \, , \, \mathrm{leads} \, f \, \mathrm{as} \, \, \mathrm{required}.$

Conditional distribution of arrivals times

- o If Y_1, \cdots, Y_n are n random variables, we define the k^p order statistic $Y_{(k)} = k^p$ smaller value among the $Y. \text{ If the } Y \text{ are IID with density } f_i \text{ then } f\left(Y_{(i)} = y_i, \cdots, Y_{(i)} = y_i\right) = n! \prod_{i=1}^n f(y_i) \\ \qquad \qquad y_i < \cdots < y_s.$ This is because given a specific set of y, there are n! ways to permute them, and each have probability $\prod f(y_i)$. Specifically, if the Y are uniformly distributed in (0, -t), then $f \left(Y_{\scriptscriptstyle (1)} = y_{\scriptscriptstyle 1}, \cdots, Y_{\scriptscriptstyle (n)} = y_{\scriptscriptstyle n} \right) = \frac{n\, t}{t^n} \qquad \qquad 0 < y_{\scriptscriptstyle 1} < \cdots < y_{\scriptscriptstyle n} < t \label{eq:spectrum}$
- Theorem: Given that N(t) = n, the n arrival times S₁,...,S_n have the same distribution as the order statistics corresponding to n IID U(0, t) random variables. In other words, each of the S, are IID U(0, t)

- $m'(t) = \mu = \mathbb{E}(X_1)$ (generalizes to the key renewal theorem). o **Proposition**: $m(t) = \sum_{i=1}^{\infty} F_n(t)$, where $F_n(t) = \mathbb{P}(S_n \leq t)$.
- $\textbf{\textit{Proof:}} \text{ Note that } N(t) = \sum\nolimits_{i=1}^{\infty} \mathbb{I}_{[S_i,S]} \Rightarrow \mathbb{E}[N(t)] = \sum\nolimits_{i=1}^{\infty} \mathbb{P}(S_i \leq t) \text{, using Fubini I}$ Remark The CDF of S. is the r-fold convolution of the CDF of each individual RV X. $F_{\scriptscriptstyle q}(\cdot) = \underbrace{F_{\scriptscriptstyle 1}(\cdot) * F_{\scriptscriptstyle 1}(\cdot)}_{} * \cdots * F_{\scriptscriptstyle 1}(\cdot)_{}. \text{ For example, } F_{\scriptscriptstyle 2}(t) = \int F(t-n) \; \mathrm{d}F(n)$
- Note that $N(t) \ge n \Leftrightarrow S_1 \le t$
- o Analogies: $m(t) \approx \lambda t$, $\mathbb{P}[N(t+h) N(t) = 1] \approx \lambda h$
- o $\mathbb{P}\left(S_{\chi(t)} \leq s\right) = \overline{F}(t) + \int_{0}^{t} \overline{F}(t-y) \, dm(y)$ $0 \leq s \leq t$

o Proposition (SLLN for renewal processes) $\frac{N(t)}{t} \rightarrow_{t=0,\infty} \frac{1}{\mathbb{E}(S_t)}$ a.s.

 $\textbf{\textit{Proof:}} \ \ \text{Consider that} \ \ S_{N(t)} \leq t \leq S_{N(t)+1}. \ \ \text{As such} \ \ \frac{s_{N(t)}}{N(t)} \leq \frac{s_{N(t)+1}}{N(t)+1} \frac{N(t)+1}{N(t)+1} \ \ \ \text{Last term goes to } 1 \ \ \text{a.s.}$ and by the SLLN, $\frac{\delta_{i}}{a} \to \mathbb{B}(X_{i})$. Feeding this into the above proves our theorem

 $\circ \quad \textit{Proposition (Elementary/Baby Renewal Theorem)}; \ \ \frac{u(t)}{t} = \frac{|\mathbf{I}[N(t)]|}{t} \rightarrow_{t \mapsto \infty} \frac{1}{|\mathbf{I}[N(t)]|}$

 $\label{eq:proof_proof} \begin{array}{lll} \textit{Proof}. & \textit{Stop} & \textit{at} & \textit{N}(t) & + & 1 & \textit{renewal.} & \textit{Stopping} \\ N(t) + 1 = n & \Leftrightarrow \textit{N}(t) = n - 1 \Leftrightarrow X_1 + \dots + X_{s-1} \leq t \; \textit{and} \; X_1 + \dots + X_s > t. \end{array}$ $\mathbb{E}(S_{\text{versus}}) = \mu[m(t) + 1]$

- Proposition (CLT for renewal processes): Suppose that $Var[X] = \sigma^2 < \infty$ then $\sqrt{t} \left(\frac{N(t)}{t} - \frac{1}{\mathbb{E}(X_i)} \right) \Rightarrow \sigma \frac{1}{\left[\mathbb{E}(X_i) \right]^{N/2}} N(0,1) \text{ Or in other words } N(t) \approx \frac{t}{\mathbb{E}(X_i)} + \sqrt{t} \frac{\sigma}{\left[\mathbb{E}(X_i) \right]^{N/2}} N(0,1)$
- $\textbf{\textit{Definition:}} \ \ \text{A distribution} \ \ F \ \text{is said to be of Lattice-type if there exists an} \ \ h>0 \ \ \text{such that} \ \ F \ \text{is}$ supported on $\{X_n\} = \{nh : n \in \mathbb{Z}\}$ For example, the Poisson distribution is lattice with h = 1
- o Theorem (Blackwell's Theorem): If F is non-lattice, then $m(t+a) m(t) \rightarrow_{local} \frac{1}{m_{X,l}} \cdot a \quad \forall a > 0$ **Remark** not implied by $\frac{m(1)}{t} \to \frac{1}{\mathbb{E}(X_1)}$, because this theorem concerns increments in m
- o Definition: A function f: \mathbb{R}_{+} → \mathbb{R}_{+} is directly Riemann integrable (dRi) if (1) $\int_{0}^{\infty} \overline{f_{i}}(x) dx < \infty$ (2) $\int_{s}^{\infty} \overline{I_{n}}(x) \ \mathrm{d}x - \int_{0}^{\infty} \underline{f}_{n}(x) \ \mathrm{d}x \rightarrow_{i=0} 0 \ . \ \text{Where} \\ \underline{f}_{n}(x) = \sum_{k=0}^{\infty} \sup \left\{ f(x) : kn \leq x \leq (k+1)n \right\} \mathbf{1}_{[a:[0,(k+1)n]]} \\ \underline{f}_{n}(x) = \sum_{k=0}^{\infty} \inf \left\{ f(x) : kn \leq x \leq (k+1)n \right\} \mathbf{1}_{[a:[0,(k+1)n]]}$

Remark: If $f: \mathbb{R}_+ \to \mathbb{R}$, we simply require both f and f to be dRi for f to be dRi **Remark**: Any of the following conditions are sufficient for $f : \mathbb{R}_+ \to \mathbb{R}$ to be dRi (1) f is continuous with compact support. (2) f is bounded and continuous, and $\int_0^\infty \overline{f_b}(x) dx < \infty$ for some h > 0. (3) f is non-increasing and $\int_{-\infty}^{\infty} f(x) dx < \infty$

$\circ \quad \text{A computer includes three parts, with exponentially distributed lives (parameters \ \lambda_i, \lambda_j, \lambda_k). \ \text{Repairs}$

- take a time X_1, X_2, X_3 to come, with arbitrary distributions and means μ_i, μ_j, μ_3 The length of time of an uptime is the minimum of three exponential variables, and so it is $\exp(\lambda_+)$. Similarly, the probability part i fails is $\lambda_i \ / \ \lambda_+$
- . Consider a renewal-reward process in which one cycle is an uptime and a downtime. The long- $\label{eq:condition} \text{run proportion of uptime is then} \quad \mathbb{E}(\text{Uptime}) \, / \, \mathbb{E}(\text{Uptime} + \text{Downtime}). \ \text{And note that}$ $\mathbb{E}(\mathrm{Downtime}) = \sum \mathbb{P}(\mathrm{Part}\ i\ \mathrm{fails}) \\ \mathbb{E}(\mathrm{Downtime}|\mathrm{Part}\ i\ \mathrm{failed}) = \sum \frac{\lambda_i}{\lambda_i} \mu_i \ . \ \mathrm{Similarly} \ , \ \mathrm{if}\ \mathrm{we'd} \ \mathrm{like}$ to find the amount of time part 2 is in suspended animation, all we need is $\mathbb{E}(\operatorname{Part}\ 2\ \operatorname{suspended}) \ / \ \mathbb{E}(\operatorname{Uptime}\ +\ \operatorname{Downtime}) \ . \ \text{Where} \ \ \mathbb{E}(\operatorname{Part}\ 2\ \operatorname{suspended}) = \frac{\lambda_i}{\lambda_i} \mu_i + \frac{\lambda_i}{\lambda_i} \mu_i$
- A truck driver goes from A to B at a fixed speed ~ U(a,b). He then goes from B to A at a speed of cither a or b (with equal probability). He then repeats with no break.
 - proportion of time spent going from A to B is $\mathbb{E}(A \to B) / \mathbb{E}(A \to B \to A)$. And note that if the distance between the two locations is d: $\mathbb{E}(A \to B) = d \int_{a}^{b} \frac{1}{r \ln a} dr = \frac{d}{b-a} \ln \left(\frac{b}{a} \right)$ and

$$\mathbb{E}(B \to A) = d \left\{ \frac{1}{2} \frac{1}{a} + \frac{1}{2} \frac{1}{b} \right\} = \frac{d(b+a)}{2ab}$$

 Similarly, we can find the proportion of time spent going at 40 miles per hour, by noting that the only time this would ever happen is going back from B to A at that speed. If we assign that event a reward of 1 per unit time, we're good. $\mathbb{E}(\text{Reward per }A \rightarrow B \rightarrow A \text{ cycle}) = \frac{1}{2} \cdot \frac{d}{dt} + 0$.

- o A regenerative process is a stochastic process with time points at which, from a probabilistic point of iew, the process restarts itself. A good example is CTMC (for example, corresponding to an M/M/1ueue). We consider that the process "resets" each time the queue empties.
- **Definition:** Let $\{X(t): t \ge 0\}$ be a stochastic process with a sample path that is right-continuous with left limits (RCLL or CADLAG). Without loss of generality, we let the renewal occur at X(t) = 0. Now, define the following quantities
 - $\tau(n+1) = \inf\{t \ge \tau(n) : X(t) = 0, X(t_-) \neq 0\}$, the time of the n^{th} renewal
 - $\tau_{n+1} = \tau(n+1) \tau(n)$, the inter-renewal time.
 - $\tilde{X}_{c}(t) = \begin{cases} X\left(\tau(n-1) + t\right) & t \in [0, \tau_{n}] \\ \Delta & t > \tau_{-} \end{cases}, \text{ where } \Delta \text{ is outside the state space of } X.$

Then X is said to be regenerative if

category i with probability $p_i(s)$. Then $N_i(t)$, the number of type-i events that have arrived by time t. is an independent Poisson random variable with mean $\lambda t p_i$, where $p_i = \frac{1}{t} \int_{t_i}^{t} p_i(s) ds$

$$\begin{split} \mathbb{P}\left(N_i(t) = n_i \ \forall i\right) &= \sum_{h=0}^{\infty} \mathbb{P}\left(N_i(t) = n_i \ \forall i \ | \ N(t) = k\right) \mathbb{P}\left(N(t) = k\right) \\ &= \mathbb{P}\left(N_i(t) = n_i \ \forall i \ | \ N(t) = n_+\right) \mathbb{P}\left(N(t) = n_+\right) \end{split}$$

Now, consider an arbitrary event in the interval (0, t). We know that the time at which that event uniformly distributed $p_i = \mathbb{P} \left(\text{It's type } i \right) = \int_{a}^{t} \mathbb{P} \left(\text{It's type } i \, | \, \text{Occured at } s \right) \mathbb{P} \left(\text{Occured at } s \right) \, \mathrm{d}t = \frac{1}{t} \int_{0}^{t} p_i(s) \, \, \mathrm{d}s$ so $\mathbb{P}\left(N_{i}(t)=n_{i}\ \forall i\mid N(t)=n_{+}\right)$ is simply $\mathbb{P}\left(N_{i}(t) = n_{i} \ \forall i \ | \ N(t) = n_{+}\right) = \frac{n_{+}!}{\prod_{i} n_{i}!} \prod_{i \neq i} p_{i}^{n_{i}}$ And so (noting that $\mathbb{P}\left(N_i(t) = n_i \ \forall i\right) = \frac{n_i \cdot !}{\prod_{i \in n} n_i !} \prod_{i \in n} p_i^{n_i} \frac{\left(\lambda t\right)^{n_i} e^{-\lambda t}}{n_i \cdot !} = \prod_{i \in \mathbb{N}} \frac{e^{-\lambda t_i} \left(\lambda t p_i^{i}\right)^{n_i}}{n_i \cdot !} \ \ \text{Which proves our theorem}$

o This theorem is useful when considering the distribution of customers that are still in service at a time t. For example, in an infinite-server queue with processing time distribution G_t let a type-I customer be one that completes its service by time t. Then for a customer that arrives at s_t p(s) = G(t - s) for $s \le t$

ogeneous Poisson Proc

- o **Definition**: A counting process $\{N(t), t \ge 0\}$ is said to be a nonhomog rate $\lambda > 0$ if (1) N(0) = 0 (2) The process has independent increments (3) $\mathbb{P}\left(N(s+t)-N(s)\right)\sim \operatorname{Po}\left(m(t+s)-m(t)\right), \text{ where } \ m(t)=\int_{s}^{t}\lambda(s) \ \mathrm{d}s \,.$
- **Definition:** A counting process $\{N(t), t \ge 0\}$ is said to be a poisson p N(0) = 0 (2) The process has stationary and independent increments. (3) $P(N(h) = 1) = \lambda(t)h + o(h)$ (4) $\mathbb{P}(N(h) \ge 2) = o(h)$
- o If $\lambda(t) \leq \lambda$ (ie: it is bounded), the process can be obtained by running a larger Poisson proc and counting an event at s with probability $\lambda(s)/\lambda$. To see why, consider that

$$\begin{split} \mathbb{P}\left(\text{One event counted} \in (t, t + \delta)\right) &= \mathbb{P}\left(\text{One event} \in (t, t + \delta)\right) \frac{\lambda(t)}{\lambda} + o(h) \\ &= h\lambda(t) + o(h) \end{split}$$

o Theorem (Key Renewal Theorem): Providing the usual assumptions on F holds (IID increm with finite mean that are not masses at 0) and that the renewal process is non-lattice, then for any $b:\mathbb{R}_+\to\mathbb{R}\quad\text{that is dRi}\quad a(t)\to_{t\to\infty}\tfrac{1}{\mu}\int_0^\infty b(s)\;\mathrm{d} s. \ \ \text{Where}\quad a\ \ \text{is a solution to remark.}$ a = b + a * F.

• Laplace Transforms & Co.

- \circ The Laplace Transform of a function of a distribution with CDF F(x) is defined as $\hat{F}(s) = \int_{0}^{\infty} e^{-st} dF(x) = \int_{0}^{\infty} e^{-st} f(x) dx$. A few important results:
 - In CDF form, if F = A * B, then $\hat{F}(s) = \hat{A}(s)\hat{B}(s)$
 - Note that if f is a density function, then |F(s)| = ∫_a[∞] e^{−x} dF(x) < 1
- Together, the points above imply that $\hat{m}(s) = \sum_{i=1}^{\infty} \hat{F}(s)^{e} = \frac{\hat{F}(s)}{1-\hat{F}(s)}$. Similarly, re-arranging $\hat{F}(s) = \frac{\phi(s)}{2\pi i k(s)}$. Thus, there is a 1-to-1 correspondence between F and m.
- o Theorem: If b(t) is bounded on any interval, then the solution to the following renewal constion $a = b + a * F \text{ (or } a(t) = b(t) + \int_0^{r_0} a(t-s) \; \mathrm{d}F(s) \text{) is } a = b + b * m \text{ (or } a(t) = b(t) + \int_0^t b(t-s) \; \mathrm{d}m(s) \text{)}$

$$o \quad \textit{Example: Consider that } \mathbb{E}[N(t)|\ X_i = x] = \begin{cases} 0 & x > t \\ 1 + \mathbb{E}[N(t) - N(x)|\ X_i = x] = 1 - m(t - x) & x \leq t \end{cases}$$

Now, $m(t) = \mathbb{E}[N(t)] = \int_{0}^{\infty} \mathbb{E}[N(t) | X_1 = k] dF(x) = \int_{0}^{t} [1 + m(t - x)] dF(x)$ $F(t) + \int_0^t m(t-x) \; \mathrm{d}F(x) = F(t) + (m*F)(t). \quad \text{ This } \quad \text{is} \quad \text{ a } \quad \text{renewal} \quad \text{ equation,} \quad \text{with } \quad \text{solution}$

 $m(t) = F(t) + \int_{-s}^{t} F(t - s) dm(s).$ Applications of the Key Renewal Theorem

o Alternating Renewal Processes

- Consider a system which can be "on" or "off". The distribution of "on" times is H, the distribution of "off" times is G and the distribution of an on-off cycle is F. We also let $P(t) = \mathbb{P}(System \text{ is "on" at time } t)$, and we let the system begin, at t = 0, at the start of an
- We can write down the following renewal equation $P(t) = \overline{H}(t) + 0 + \int_{-t}^{t} P(t-s) dF(s)$. This equation reflects the fact that, at t (1) Either the first "on" period hasn't finished yet... (2) ...or it has finished and we're in the "off" period... (3) ...or it has finished, and so has the subsequent "off" period, and the total cycle took a period s < t. In which case, we simply restart with P(t - s).
- $\tilde{X}_{\scriptscriptstyle 0}, \tilde{X}_{\scriptscriptstyle 1}, \cdots$ are independent
- $\bullet \quad \check{X}_i, \check{X}_i, \cdots \text{ are identically distributed (the first renewal might have a different distribution if the distribution of the distribut$ the system doesn't start "empty").
- **Definition** (recurrence): A regenerative process is positive-recurrent if $\mathbb{E}(\tau_i) < \infty$ and null
- Proposition (SLLN for regenerative processes): Let $(X(t): t \ge 0)$ be a regenerative process over a state space $\mathcal S$ with $\mathbb B(\tau_i)<\infty$, and let $f:\mathcal S\to\mathbb R$ be such that $\mathbb B\Big(\int_{\tau(0)}^{\tau(1)}\Big|f\big(X(s)\Big|\Big)\,\mathrm ds\Big|<\infty$.

$$\frac{1}{t} \int_{s}^{t} f(X(s)) ds \rightarrow \frac{\mathbb{E}\left(\int_{-(0)}^{r(1)} f(X(s)) ds\right)}{\mathbb{E}(\tau, \cdot)} \text{ a.s. as } t \rightarrow \infty$$

o Proposition (CLT for regenerative processes): Let $(X(t): t \ge 0)$ be a regenerative process on a state space S with $\mathbb{E}(\tau^2) < \infty$. Let $f : S \to \mathbb{R}$ be a function satisfying $\mathbb{E}(Y_i(|f|)^2) < \infty$. Then

$$\sqrt{t}\left|\frac{\int_{0}^{t} f(X(s)) ds}{t} - \frac{\mathbb{E}(Y_{i}(t))}{\mathbb{E}(T_{j})}\right| \Rightarrow \sigma N(0,1)$$

With $\sigma^2 = \mathbb{E}(Y_i^2(f_i)) / \mathbb{E}(\tau_i)$ where $f_i(\cdot) = f(\cdot) - \frac{\mathbb{E}(1_i(f))}{\mathbb{E}(\tau_i)}$

- Theorem: Let $\{X(t): t \ge 0\}$ be a positive recurrent regenerative process on a state space $S \subseteq \mathbb{R}^{\ell}$ Suppose that either of the following conditions hold
 - F(x) = P(τ, −x) has a density and there is a function h: Rst → R that is bounded
 - F(x) = P(τ, -x) is non-lattice and there is a function h that is bounded and continuous

Then
$$\mathbb{E}[b|X(t)] = \frac{\mathbb{E}\left[\int_{-\infty}^{\infty} R(X(s)) \, ds\right]}{\mathbb{E}[\tau_i]}$$
 as $t \to \infty$ Then $X(t) \Rightarrow X(\infty)$ as $t \to \infty$ and
$$\mathbb{P}\left(X(t) \in A\right) = \frac{\mathbb{E}\left[\int_{-\infty}^{\infty} |I_{(1)}(s) - ds\right]}{\mathbb{E}[\tau_i]}$$

Remark If $X(0) =_{t} X(\infty)$, then $(X(t): t \ge 0)$ is stationary

- Definition: A stochastic process $\{N(t), t \geq 0\}$ is said to be a counting process if N(t) represents Fundher of events that have occurred up to time ℓ^* . Hence: (1) $N(t) \ge 0$ (2) N(t) is integer valued (3) $s < t \Rightarrow N(s) \le N(t)$ (4) For s < t, N(t) - N(s) = number of events in (s,t]
- - o Proposition: Consider a situation in which, as events arrive at time s, they get cl category i with probability $p_i(s)$. Then $N_i(t)$, the number of type-i events that have arrived by time t, is an independent Poisson random variable with mean $p_i = \int_0^t \lambda(s) p_i(s) \ \mathrm{d}s$.

Proof. Consider a larger Poisson process with rate $\lambda \ge \lambda(t)$. From our previous proposition, we then have that $p_i = \Lambda \int_0^t \frac{\lambda(s)}{\Lambda} p_i(s) ds = \int_0^t \lambda(s) p_i(s) ds$

· Compound Poisson Pr

- o If X_1, X_2, \cdots are IID with distribution F, independently of $N \sim Po(\lambda)$, then $W = \sum_{i=1}^{N} X_i$ is a compound Poisson variable
- o Properties
 - $\blacksquare \quad M_{\scriptscriptstyle W}(s) = \mathbb{E} \Big[\mathbb{E} \Big(\exp(sX_{\scriptscriptstyle *}) \Big)^{\epsilon} \Big] = \mathcal{G} \Big(M_{\scriptscriptstyle X}(s) \Big) = \exp \Big(\lambda t [M_{\scriptscriptstyle X}(s) 1] \Big)$
 - $\mathbb{E}(W) = \lambda \mathbb{E}(X)$ and $Var(W) = \lambda \mathbb{E}(X^2)$
- contribute an amount X whose value is a random variable with distribution F. Even though the X are neither identical nor independent, the variable $W(t) = \sum_{i=1}^{N(t)} X_i$ is then a compound Poisson

random variable with rate $\lambda = \alpha t$ and distribution $F(x) = \frac{1}{t} \int_0^t F_i(x) ds$. **Proof.** Consider a given event i at a time $s \in (0, t)$.

 $\mathbb{P}(X_i \leq x \mid s) = F_i(x)$

But we know that $s \sim U(0,t)$, so

$$\mathbb{P}\big(X_i \leq x\big) = \mathbb{E}\big[\mathbb{P}\big(X_i \leq x \, | \, s\big)\big] = \frac{1}{t} \int_{s=0}^t F_s(x) \; \mathrm{d}s$$
 Now, consider that

Proof. Consider numbers n_1, \dots, n_r , and note that

$$M_{ir}(\tau) = \mathbb{E} \Big[e^{\tau W} \Big) = \mathbb{E} \Big[\mathbb{E} \Big(e^{\tau S_i} \Big)^n \Big] = \mathbb{E} \Big[M_{\chi_i}(\tau)^n \Big] = \exp \Big(\lambda t \Big\{ M_{\chi_i}(\tau) - 1 \Big\} \Big)$$

Important application II. If F is discrete, such that $\mathbb{P}(X_i = j) = p_j$, and we define $N_i =$ number of events of type j that occur, we can also write $W = \sum_{ij} j N_j$ $N_r \sim \text{Po}(\lambda p_r)$

$$\begin{split} \mathbb{P} \left(N_i = n_i \ \forall i \right) &= \sum_{k=0}^{\infty} \mathbb{P} \left(N_i = n_i \ \forall i \ | \ N = k \right) \mathbb{P} \left(N = k \right) \\ &= \mathbb{P} \left(N_i = n_i \ \forall i \ | \ N = n_+ \right) \mathbb{P} \left(N = n_+ \right) \end{split}$$

And note that the first probability is multinomial.

 $\text{distribution } G. \text{ So, for example } \mathbb{P} \left(N(t+s) - N(s) = n \right) = \int_0^\infty e^{-u} \frac{(\lambda t)^s}{u!} \ \text{d} G(\lambda)$

Is a Poisson processes, because $N(t + s) - N(s) = n \mid \Lambda = \lambda - Po(\lambda t)$ o Given N(t)=n, the conditional distribution of Λ is

$$\begin{split} \mathbb{P}\left(\Lambda \leq x \mid N(t) = n\right) &= \frac{\mathbb{P}\left(\Lambda \leq x \text{ and } N(t) = n\right)}{\mathbb{P}\left(N(t) = n\right)} = \frac{\int_{0}^{\infty} \mathbb{P}\left(\Lambda \leq x \text{ and } N(t) = n \mid \Lambda = \xi\right) \, \mathrm{d}G(\xi)}{\int_{0}^{\infty} \mathbb{P}\left(N(t) = n \mid \Lambda = \lambda\right) \, \mathrm{d}G(\lambda)} \\ &= \frac{\int_{0}^{\infty} \mathbb{P}\left(N(t) = n \mid \Lambda = \lambda\right) \, \mathrm{d}G(\lambda)}{\int_{0}^{\infty} \mathbb{P}\left(N(t) = n \mid \Lambda = \lambda\right) \, \mathrm{d}G(\lambda)} = \frac{\int_{0}^{\infty} \mathbb{P}\left(N(t) = n \mid \Lambda = \lambda\right) \, \mathrm{d}G(\lambda)}{\int_{0}^{\infty} \mathbb{P}\left(N(t) = n \mid \Lambda = \lambda\right) \, \mathrm{d}G(\lambda)} \end{split}$$

- o If $Y = \min(X_1, X_2)$ and $Z = \max(X_1, X_2)$, finding the covariance between them is simplified by writing Z = Y + W, where W is independent of Y. Note that W is a mixture distribution; it either takes the parameter of X_1 or of X_2 , with probabilities defined at the start of this section ("Important
- \circ $N(t) = N_i(t) + N_i(t)$. Probability that first event of combined process is from N is $\mathbb{P}\left(N_i(t)=1\mid N(t)=1\right)=\mathbb{P}\left(N_i(t)=1,N_i(t)=0\right)/\mathbb{P}\left(N(t)=1\right).$
- Find the joint distribution of S_1 , S_2 , S_3 . We know the joint distribution of X_1 , X_2 , X_3 , and we know that $(S_{-}, S_{\alpha}, S_{\alpha}) = (s_{-}, s_{\alpha}, s_{\alpha}) \Leftrightarrow (X_{-}, X_{\alpha}, X_{\alpha}) = (s_{-}, s_{\alpha} - s_{-}, s_{\alpha} - s_{\alpha}).$
- o N(t) is Poisson process with rate λ . Mark first event after a If haven't stopped by T, lose. If event occurs before T and after mark, lose. $\mathbb{P}(\text{Winning}) = \mathbb{P}(1 \text{ event } \in (s, T)) = \lambda(T - s)e^{-\lambda T}$.
- \circ Cars arriving with Poisson process; cross if next car will arrive in more than T minutes. Condition on $t \qquad \text{till} \qquad \text{next} \qquad \text{car} \qquad \mathbb{E} \Big(\text{Wait} \big) = \int_0^\infty \mathbb{E} \Big(\text{Wait} \, | \, \, \text{Next in } x \Big) \lambda e^{-\lambda t} \, \, \, \mathrm{d}x \,, \qquad \text{and} \qquad \text{note} \qquad \text{that}$ $\mathbb{E} \big(\mathrm{Wait} \ | \ \mathrm{Next \ in} \ x \big) = \Big\{ x + \mathbb{E} \big(\mathrm{Wait} \big) \! \Big\} \mathbb{I}_{s \in \mathbb{F}}.$
- Shocks occur with Poisson process. Each might cause failure (independently) with probability p. Can consider two Poisson processes: "failing events", with rate λp , and "non-failing events", with rate $\lambda(1-p)$. Num shocks | $T = t \sim \text{Po}(\lambda(1-p)t)$.
- Number of trials is Po(λ). Each results in outcome i with p. X. is total number of outcomes that curs j times. Write $X_i = \sum I_i$, where I_i is 0 if event i occurs j times
- f_g (x | N(t) = n): use the fact that S_i is the tth smallest of n random variables. i − 1 of these variable must be > x than i, and n - i of them must be < x. Thus

$$f_{\boldsymbol{\theta}_i}(\boldsymbol{x} \mid N(t) = n) = \frac{n!}{(i-1)!(n-i)!} \big[F(\boldsymbol{x}) \big]^{i-1} \big[\overline{F}(\boldsymbol{x}) \big]^{i-1} f(\boldsymbol{x})$$

Where f is the distribution of a uniform (0, t).

to obtain the RHS, we add an additional constraint to the LHS. For example, the LHS of the first equation talks of getting from j back to j in n + m steps. The RHS talks of going from jto i in n steps, and then back to j in m additional steps.

These two equations imply that d(j) divides both n + m and n + m + s; and therefore also divides their difference, which is equal to s. Thus any s that is divisible by d(i) is also divisible by d(j). A similar argument yields the other direction, giving d(i) = d(j).

Intuitively, we are simply finding a way of getting from state j back to itself via i, and then realize that we can add s to that number no problem by looping at i an appropriate number of

 Definition (Recurrence): For any states i and j, define f_i^c to be the probability that starting in i, the first transition into j occurs at time n.

$$f_{a}^{0} = 0$$
 $f_{a}^{e} = \mathbb{P}(X_{a} = j, X_{b} \neq j \ \forall k = 1, \dots, n-1 \ | \ X_{b} = i)$

We let $f_a = \sum_{i=1}^{\infty} f_a^a$. It is the probability of ever making a transition into state j_i given the process starts in i. We say state j is recurrent if and only if $f_{ij}=1$, and transient otherwise.

Theorem: Sate j is recurrent if and only if $\sum_{n=1}^{\infty} P_{jj}^{n} = \infty$

Proof. State j is recurrent if and only if $\mathbb{E}(\text{Number of visits to } j | X_n = j) = \infty$ (if the state were not recurrent, each time the state was entered, there would be a fixed probability of never returning there, leading to a geometrically distributed number of visits with finite

$$\mathbb{E} \big(\text{Number of visits to } j \mid X_0 = j \big) = \sum\nolimits_{n=0}^{\infty} \mathbb{E} \Big(\mathbb{I}_{\{X_n = j\}} \mid X_0 = j \Big) = \sum\nolimits_{n=0}^{\infty} P_j^n$$

Theorem: Recurrence is a class property; if $i \mapsto j$ and i is recurrent, then j is recurren **Proof**: Intuitively, if we can get from j to i and back (since $i \leftrightarrow j$) and we know we'll always get back to i if we leave from there, then we can necessarily also always get back to j.

More formally, find m and n such that $P^n > 0$ and $P^n > 0$, we then have $P_{jj}^{n+n+z} \ge P_{ji}^{n} P_{ij}^{n} P_{ij}^{n} > 0$. As such $\sum P_{jj}^{n+n+z} \ge P_{ji}^{n} P_{ij}^{n} \sum P_{ij}^{z} = \infty$

 $\blacksquare \quad \text{Another way of defining a recurrent state is to let } \ T_i \text{ be the first return time to state } \ i \text{ when}$ the system starts at $X_i = i$. An event is transient if and only if $\mathbb{P}(T = \infty) > 0$. Even for recurrent events, the expectation of T_i need not be finite. Indeed, we define.

Definition (positive recurrence and null recurrence): Let

$$\mu_{i} = \mathbb{E}(T_{i}) = \begin{cases} \infty & \text{if } i \text{ is transient} \\ \sum_{i=1}^{n} n f_{i}^{a} & \text{if } i \text{ is recurrent} \end{cases}$$

We say event i is positive recurrent if $\mu_{ii} < \infty$, and null recurrent otherwise

Proof. detailed balance equations reduce to $\pi_i w_{ij} / \sum_i w_{ik} = \pi_j w_{ji} / \sum_i w_{jk}$. We have, that $w_{ij} = w_{ji}$. and so $\pi_i / \sum_k w_k = \pi_j / \sum_k w_k \Rightarrow \pi_i \propto \sum_k w_k$. Since the π must sum to 1, the result is as above Theorem: If we have a Markov chain with transition probabilities P_r and we can find a vector π

and a matrix P^* such that $\pi_i P_n = \pi_i P_n^*$, then the π are stationary probabilities and P^* is the transition matrix of the reversed chain.

- Consider a 3 by 3 grid in which an unfortunate mouse is free to move (but not diagonally). The cells are labeled 1 to 9, left-to-right and then top-down. This is a periodic markov chain with period 2, since we can only ever go from an odd state to an even state and vice-versa. We can work out various limiting probabilities intuitively
 - $(P^{2b})_{1,2} \approx \frac{1}{4}$, because by symmetry, the probability of being in each even state is equal in the long-run. So $P_{1,1}^{20} \approx P_{1,1}^{20} \approx P_{2,4}^{20} \approx P_{1,1}^{20}$, and the sum is equal to 1.
 - $\bullet \quad \overline{(P^{2^{n+2}})_{;2} = \frac{1}{4}} \; , \; \text{because the long run probability of being in any even state, starting at any leaves the long run probability of being in any even state, starting at any leaves the long run probability of being in any even state, starting at any leaves the long run probability of being in any even state, starting at any leaves the long run probability of being in any even state, starting at any leaves the long run probability of being in any even state, starting at any leaves the long run probability of being in any even state, starting at any leaves the long run probability of being in any even state, starting at any leaves the long run probability of being in any leaves the long run probability of being in any leaves the long run probability of leaves the leaves the long run probability of leaves the leaves the long run probability of leaves the leaves the long run probability of leaves the long run probability of leaves the leaves the long run probability of leaves the leaves the long run probability of leaves the leav$ state, is equal. Or in other words, $P_{1,2}^{28+1} = P_{1,2}P_{2,2}^{28} + P_{1,4}P_{4,2}^{28}$
 - $\blacksquare \quad \overline{(P^{2b})_{i,1} \approx \frac{1}{4}} \; \text{, because} \; (P^{2b})_{i,1} = P_{1,2}^{2b-1} P_{2,1} + P_{1,4}^{2b-1} P_{4,1}.$
 - $\blacksquare \quad \overline{\left(P^{26}\right)_{i,k} \approx \frac{1}{4}}, \quad \text{because} \quad P^{2c}_{i,k} = \sum_{z=(2,4,6,8)} P^{2b-1}_{i,k} P_{z,k} = 4 \cdot \frac{1}{4} \cdot \frac{1}{4}. \quad \text{Alternatively}, \quad \text{note} \quad \text{that} \quad \text{the}$ probability of being in any odd cells adds up to 1, and the probability of being in each of the cells 1, 3, 7 and 9 is $\frac{1}{6}$.
 - $(P^{2k})_{i,k} \approx \frac{1}{3}$, because $P^{2k}_{i,k} = \sum_{i=\{2.4,6.8\}} P^{2k-i}_{i,i} P_{i,k}$
- Consider an M/G/1 queue. Let X_n be the number of customers left in the queue just after the nⁿ customer has departed. This is an embcdded Markov chain. Let Y_e denote the number of customers that arrive during the service time of the n^α customer: $X_{n+1} = \begin{cases} X_n - 1 + Y_{n+1} \\ Y_{n+1} \end{cases}$

The chain is clearly irreducible. Let's try and check whether it's positive recurrent or transient. We $\hat{\pi}(s) = \sum\nolimits_{j=0}^{\infty} \pi_j s^j \ \text{ and } \ \hat{A}(s) = \sum\nolimits_{j=0}^{\infty} a_j s^j \text{ . We then multiply the above equation by } s^i \text{ on both sides},$

- o $M/G/\infty$ queue. Type I event if departs in (s, s+t). It's a Poisson process, with the right rate. To prove independent, type I if leaves in I_1 , type II if leaves in I_2 ($I_1 \cap I_2 = \emptyset$) and type III otherwise All independent.

$$Cov(N(t,), N(t,)) = Cov(N(t,), N(t,) + N(t,) - N(t,)) = Cov(N(t,), N(t,))$$

Markov Chains

- · We assume everything is time homogeneous
- $i \sim j$ means that $\mathbb{P}_i(T_i < \infty) > 0$.
- Definition (Positive Recurrence): P_i(T_i < ∞) = 1 means the state is recurrent. If E_i(T_i) < ∞ m that it's positive recurrent.
- Result: If the chain is irreducible, the following are equivalent

 - o All states are positive recurrent (and therefore the chain is positive recurrent)
 - The chain has an invariant distribution π
- The "ratio" formula for the steady state distribution is

$$\pi_i = \mathbb{P}_{-}\{X_{-} = i\} = 1 / \mathbb{E}_{i}(T_i)$$

 $\pi_i = \mathbb{P}_{\pi}\left\{X_{\alpha} = i\right\} = 1/\left|\Xi_i(T_i)\right|$ In the finite state space, it is enough to solve the following set of equations to find the steady st

$$\pi^{\rm T}P=\pi^{\rm T} \qquad \pi_{\pm}=1$$
 Whereas for a countable state space, we need those two equations and either $\pi\geq \theta$ or $\sum |\pi|<\infty$

• Result: For a finite state space, suppose we have $P_{ii}^n \to \pi_i$ as $n \to \infty$ for some j, i, then π_j is the invariant sure of the state i.

Definition: A state i is aperiodic if $P_{\alpha}^{\alpha} > 0$ eventually.

Theorem: For a irreducible, aperiodic Markov Chain for which there is a stationary distribution π ,

$$P_{ij}^{e} \rightarrow \pi_{j}$$
 as $n \rightarrow \infty \ \forall i, j \in \mathcal{S}$

In other words, $\mathbb{P}_{r}(X_{s} = j) \rightarrow \mathbb{P}_{r}(X_{0} = j)$.

Let $X_c n \ge 0$ be a Markov Chain on a state space S which is irreducible [countable state space] Let λ be any distribution over S. The nfor X_e - \lambda.

$$\frac{N_i(n)}{n} = \frac{\sum_{k=1}^n \mathbb{1}_{\{X_i = i\}}}{n} \to_{s.s.} \frac{1}{\mathbb{B}_i(T_i)}$$

For all $i \in \mathcal{S}$,

Theorem: Assume the same setup as previous ergodic theorem and in addition that the chain is positive recurrent and aperiodic. Then for any bounded f for $f : S \rightarrow \mathbb{R}$, then

$$\frac{1}{n}\sum_{i=1}^{n} f(X_{i}) \rightarrow \mathbb{E}_{x}f(X_{0}) = \sum_{k \in S} \pi_{k}f(k)$$

• Introduction & Transition Probabilities

Theorem: Null recurrence is a class property

- o Types of Markov Chains more formally
 - Definition (aperiodicity): A class is said to be aperiodic if it has period 1. A Markov chain is said to be apcriodic if every one of its classes has period 1.
 - Definition (irreducibility): A Markov chain is said to be irreducible if it has a single class.
 - Definition (ergodicity): A state is said to be ergodic if it is aperiodic and positive recurrent. A Markov chain is said to be croodic if every one of its states is ergodic.

- A probability distribution π is said to be stationary for a Markov chain with probability transition
- o Theorem: An irreducible, aperiodic Markov chain belongs to one of the following two classes
 - Either all the states are transient or null recurrent [in which case, $\lim_{n\to\infty} P_0^n = 0 \quad \forall i, j$, and there exists no stationary distribution].
 - Or all states are positive recurrent, with $\pi_i = \lim_{n \to \infty} P_n^n > 0$ π is a stationary distribution, and there exists no other stationary distribution. Notes: (1) In that case, the chain is ergodic. (2) The distribution π can be found by solving $\pi = \pi P$ together with $\sum \pi = 1$. (3) Note that if the Markov chain has a finite number of states, this is the only option. (4) It turns out that $\pi_j = 1 / \mu_g$; the long-term probability of transitioning into a state is the reciprocal of the expected time till the state is returned to. Thus, if $\pi_j = 0$
- our state is null-recurrent. o. If the chain is periodic, things change slightly. The stationary vector π is still the long run proportion of time the Markov chain is in state j, but because of the periodicity, this is now ex- $\lim_{s\to\infty}\frac{P_n^{sd}}{d}=\pi_i$. To see why, consider that P_n^{sd} is the average proportion of time spent in state iamongst all the other states in the same "periodicity class". We need to divide by d to ensure we are accurately finding the proportion of time spent in all the states

Non-irreducible Markov chain

 We now consider non-irreducible Markov chain. The interesting case is one in which there are some recurrent classes. We partition the transition matrix as follows: $P = \begin{bmatrix} \iota & 0 \\ R & Q \end{bmatrix}$. Where Q only contains

transient states (ie: it denotes the probabilities of motion amongst the transient states), and Rcontains the one-step absorption probabilities. The matrix ℓ will be equal to I if all recurrent states are absorbing; otherwise, it represents the probabilities of motion amongst the recurrent states).

$$\begin{split} \hat{\pi}(s) &= \pi_{\alpha}\hat{A}(s) + \sum_{j \neq 0} \sum_{s' = 1}^{j+1} \pi_{\beta_{j-1+1}}s^{j} \\ \hat{\pi}(s) &= \pi_{\theta}\hat{A}(s) + \frac{1}{r} \sum_{j' = 1}^{m} \pi_{\beta}^{s} \sum_{s' = 1}^{s+1} a_{j+1+1}s^{j+1+1} \\ \hat{\pi}(s) &= \pi_{\theta}\hat{A}(s) + \frac{1}{r} \sum_{j' = 1}^{m} \pi_{\beta}^{s} \sum_{s' = 0}^{m} a_{j}s^{s} \\ \hat{\pi}(s) &= \pi_{\theta}\hat{A}(s) + \frac{\pi_{\theta}(s) - \pi_{\theta}}{s} \hat{A}(s) \\ \hat{\pi}(s) &= \frac{(s - 1)\pi_{\theta}\hat{A}(s)}{s - \frac{1}{4}A(s)} \end{split}$$

To find π_a , we let $s \to 1$, and note that $\lim_{s \to 1} \hat{A}(s) = \sum_{s=0}^{\infty} a_s = 1$, whereas $\lim_{s \to 1} \hat{\pi}(s) = \sum_{s=0}^{\infty} \pi_s$ Using L'Hopital's rule, we find: $\lim_{s\to 1} \hat{\pi}(s) = \pi_0 [1 - A'(1)]^{-1}$. Consider, however, that

$$A'(1) = \sum\nolimits_{j=0}^\infty ja_j = \mathbb{E} \left(\text{Arrivals during service time} \right) = \lambda \mathbb{E} \left(\text{Service time} \right) = \rho$$

Thus $\sum_{j=0}^{\infty} \pi_j = \frac{\pi_0}{1-\rho}$. For the chain to be recurrent, this sum must be equal to 1. Thus, this can only occur when $\rho < 1$, in which case $\pi_{\alpha} = 1 - \rho$. In that case, we get

$$\hat{\pi}(s) = \frac{\left(1 - \rho\right)\left(s - 1\right)\hat{A}(s)}{s - \hat{A}(s)} = \frac{\left(1 - \lambda \mathbb{E}(S)\right)\left(s - 1\right)\hat{A}(s)}{s - \hat{A}(s)}$$

 We can take the derivative of this, and let z → 1. This gives us the expected number of people in the system. The details are horrible, and involve multiple applications of L'Hopital's

$$\text{Rule } \mathbb{E}\left(Q_{\infty}^{\rho}\right) = \rho + \frac{\rho^2}{1-\rho} \frac{\left(c_s^2+1\right)}{2} \, \text{. Where } c_s^2 = \mathbb{Var}(S) \, / \, \mathbb{E}(S)^2.$$

- o Let $\mathbb{P}(X = j) = a$, where $j = 0, \pm 1, \pm 2, \cdots$. Let $S_a = 0$ $S_a = \sum_{i=1}^{n} X_i$. Then S_a is a Markov chain, for which $P_{ij} = a_{j-i}$. Consider the situation in which $a_1 = p$ and $a_{-1} = 1 - p$. It is then clear that the chain is irreducible and periodic with d=2; thus, $P_{00}^{2i+1}=0$. However, using $n! - n^{n+\frac{1}{2}} e^{-n} \sqrt{2\pi} \;, \;\; \text{we have} \quad P_{\infty}^{2n} = \begin{bmatrix} 2n \\ n \end{bmatrix} p^n (1-p)^n \\ = \frac{(2n!)}{n!n!} [p(1-p)]^n - \frac{1}{\sqrt{\pi n}} [4p(1-p)]^n \;. \;\; \text{The series}$
- $\sum P_{00}^{2a} \ \ \text{therefore only converges if} \ \ 4p(1-p) \leq 1 \text{, which only occurs at } p = \%. \text{ Thus, the symmetric of the symmetric o$ simple random walk is recurrent. Other simple random walks are transient.
- o. Suppose a battery fails at period i with probability p_{ii} where p_{i} as aperiodic and $\sum_{i}ip_{i}<\infty$. Let X_{0} denote the age of the battery in use at period s. This is a Markov chain, with probability $P_{_{i,1}} = 1 - P_{_{i,i+1}} = p_{_i}$ $i \geq 1$. To find the stationary distribution, solve $\pi = \pi P$. In this case this reduces to $\pi_i = \sum_i \pi_i p_i \Rightarrow \pi_{i+1} = \pi_i (1-p_i)$ $i \ge 1$. Iterating the second equation, we obtain $\pi_{i+1} = \pi_i \prod_{j=1}^i (1-p_j) = \pi_i \sum_{j=i+1}^\infty p_j = \pi_j \mathbb{P}\left(X \geq i+1\right). \text{ Using the fact that the sum of all the } \pi \text{ has } T = 0$ to be 1, we get that $\pi_i = 1 / \mathbb{E}(X)$. Thus, we find $\pi_i = \mathbb{P}(X \ge i) / \mathbb{E}(X)$, which can easily be seen to satisfy the first equation above.

 $\circ \ \mathbb{P}\left(X_{s+1}=j \mid X_s=i, X_{s-1}=i_{s-1}, \cdots\right) = P_{s} \ \text{This is called the Markovian property}$

- We let P denote the matrix of one-step transition probabilities P_{η} Since the cor are probabilities, we have $P_{ii} \ge 0$ $\sum_{n} P_n = 1$
- o The n-step transition probabilities P_i^a give the probability that a process in state i will be in state j
- after n additional transitions $P_n^s = \mathbb{P}(X_{con} | X_n = i)$ $n \ge 0$, $i, j \ge 0$

Chapman-Kolmogorov Equations: The n-step transition promultiplication $P^{e+e} = P^n P^n$ $\forall n, m \ge 0$

$$\begin{split} P_{v}^{\text{nin}} &= \mathbb{P}\big(X_{*+w} = j \mid X_{0} = i\big) = \sum_{su} \mathbb{P}\big(X_{s+w} = j, X_{c} = k \mid X_{0} = i\big) \\ &= \sum_{uv} \mathbb{P}\big(X_{w+w} = j \mid X_{c} = k, X_{c} = i\big) \mathbb{P}\big(X_{0} = k \mid X_{0} = i\big) \\ &= \sum_{vv} \mathbb{P}\big(X_{v+w} = j \mid X_{c} = k, X_{c} = i\big) \mathbb{P}\big(X_{c} = k \mid X_{0} = i\big) = \sum_{vv} P_{v}^{u} P_{s}^{u} \end{split}$$

- es of Markov chain Markov chains come in different types and flavours. The main distinction
 - Irrcducible/crgodic Markov chains in which every state can be reached from every other state.
 Non-irrcducible Markov chains, in which some states cannot be reached from other states. An
 - example is chains containing one or more absorbing element i, for which $P_a = 1$

Proof: Consider that

- Definition (Communicating states): State j is said to be accessible from state i if, for some $n \ge 0$, $P_{ii}^n > 0$. If two states are accessible to each other, we write $i \leftrightarrow j$ and say states iand j communicate. Notes:
 - Communication is an equivalence relation. In other words: (1) i ↔ i (2) i ↔ j ⇔ j ↔ i (3) $i \leftrightarrow j$ and $j \leftrightarrow k \Rightarrow i \leftrightarrow k$
 - Two states that communicate are said to be in the same class. Any two classes are
 either disjoint or identical, so the set of states is partitioned into classes.
- Definition (irreducible chain): If a Markov chain contains only one class, it is clearly irreducible, since every item in the class can be reached from every other item

 Definition (Period): State i is said to have period d, denoted d(i), if P' = 0 whenever n is not divisible by d, and d is the greatest integer with this property. (1) A state with period 1 is said to be approache. (2) If $P^* = 0$ for all n > 0, then we say the period of i is infinite

Theorem: Period is a class property; if $i \leftrightarrow j$, then d(i) = d(j).

Proof. Suppose $P_{ii}^s > 0$; in other words, s is divisible by d(i). Furthermore, choose some mand n such that $P_c^*P_c^* > 0$; this is clearly possible since the staes communicate. Then $P_{\nu}^{n+n} \ge P_{\nu}^{n} P_{\mu}^{n} > 0 \Rightarrow P_{\mu}^{n+n+s} \ge P_{\nu}^{n} P_{\mu}^{s} P_{\mu}^{n} > 0$. To see why these inequalities hold, consider that

o **Theorem:** If ρ is a recurrent class of states and $i \in \rho$, $j \neq \rho$, then $P_{ii} = 0$.

es, and therefore do not communicate. Thus, if we had $P_v > 0$, we would have to have $P_i^i = 0$ for all n. Hence, if the process starts at i, there is a positive probability it might end up in j and then never return to i; this contradicts the fact i is recurrent.

on arises, therefore, of how many times we visit any given state before being N_v be the expected number of times spent in transient j, given we started in state i.

Now, we write $N_{\alpha} = \sum_{i=n}^{\infty} \mathbb{P}\left(\text{End up in } j \text{ after } k \text{ moves if started at } i\right) = \mathbb{I}_{i=n} + Q_{\alpha} + Q_{\alpha}^2 + Q_{\alpha}^2 + \cdots$ Since Q is a matrix of transient states, its rows do not sum to 1 and $Q^0 \rightarrow 0$, so the equation above makes sense. In matrix notation, we have $N=I+Q+Q^2+\cdots \Rightarrow (I-Q)N=I \Rightarrow N=(I-Q)^{-1}$ This is called the fundamental matrix of the Markov chain.

- We can also find the expected number of step until absorption given a start in state i denote this M_i . Clearly, this is simply the sum of the times we will spend in each transient state. Thus, M=NIAnother, equivalent, way of obtaining this quantity is writing each equation manually $M_i = 1 + \sum_{n_i} P_{in} P_{n-interest + interest}$
- o Similarly, let B_{il} be the probability of being absorbed into state ℓ given a start in state i. We can $\begin{aligned} & \text{write } & B_{\bowtie} = \sum_{k=0}^{\infty} \mathbb{P} \left(\text{Absorbed into state } \ell \text{ after step } k \text{ if started at } i \right) \\ & = B_{\bowtie} + \sum_{n} Q_{\bowtie} B_{\bowtie} + \sum_{n>p} Q_{\bowtie} Q_{p} B_{p\ell} + \cdots \end{aligned}$

In matrix form
$$B=R+QR+Q^2R+\cdots=(I+Q+Q^1+\cdots)R=NR$$
. Again, in the absence of a computer, we often need to do this manually. This can be done using a recurrence relation

 $B_{il} = \sum_{k \in \text{Framework}} P_{ik} B_{kl} + \sum_{\substack{k \in \text{Outlies} \\ \text{communications}}} P_{ik}$

Take a Markov chain whose initial state is chosen to be equal to π. We can then imagine the chain was started at $\,t=-\infty$. The "reverse chain" is then also a Markov chain, with transition probabilities

$$P_{ij}^{*} = \mathbb{P}\left(X_{n} = j \mid X_{n+1} = i\right) = \frac{\mathbb{P}\left(X_{n+1} = i \mid X_{n} = j\right)\mathbb{P}\left(X_{n} = j\right)}{\mathbb{P}\left(X_{n+1} = i\right)} = \frac{P_{j}x_{j}}{\pi_{j}}$$

- We say a Markov chain is time reversible if P = P': in other words. P satisfies the detailed balance equations $\pi_i P_a = \pi_i P_a$ $\forall i, j$. These equations imply $\pi = \pi P$ (to see why, simply sum over j); thus it is enough to check for the second equation. These equations can be interpreted as stating that the rate at which the process goes from i to j is the same as the reverse rate.
- $_{\odot}$. Consider a graph with a positive number w_{g} associated with each edge. Suppose a particle currently on vertex i moves to vertex j with probability $P_{ij}=w_{ij} / \sum_{\gamma_j} w_{ij}$. This is a Markov chain, and if it is irreducible, then it is, in steady state, time-reversible with stationary probabilities given by

$$\pi_i = \sum_{ij} w_{ij} / \sum_{ij} \sum_{ij} w_{ij}$$

- o. During each time period, every member of a population dies with p, and $\operatorname{Po}(\lambda)$ new members join X_s , the population during period n, is a Markov chain. Note that if $X_s = \alpha$, then $X_i \sim \text{Po}[\alpha(1-p) + \lambda]$. Thus, if we choose α to satisfy $\alpha = \alpha(1-p) + \lambda$ [ie: $\alpha = \lambda / p$], the chain is stationary, with $\pi_j = \mathbb{P}[Po(\frac{\lambda}{g}) = j]$.
- Let P^t_{i,i,i} be the probability that, starting in state i, the Markov chain will end up in state j without ever passing through state k. We can show that $P^s_{ij} = \sum_{k=0}^{n} P^{s-k}_{ijk} P^k_{ii}$. Intuitively, we can split our journey from i to j into two parts – the first part perambulating around and possibly returning to i a number of times, and the last part finally heading from i to j. To prove, let Y be the last time we leave state i. Now $P^{i}_{ij}=\mathbb{P}(X_{\pi}=j\mid X_{b}=i)=\sum_{i=0}^{n}\mathbb{P}(X_{\pi}=j,Y=k\mid X_{0}=i)$
- $= \sum_{k=0}^{a} \mathbb{P}(X_{n} = j, Y = k, X_{k} = i \mid X_{0} = i) = \sum_{k=0}^{a} \mathbb{P}(X_{n} = j, Y = k \mid X_{k} = i) \mathbb{P}(X_{k} = i \mid X_{0} = i)$ $=\sum_{k=0}^{n}P_{\eta |h}^{o-k}P_{u}^{k}$ To go from the second to the third step, the thought-process involves the fact that ng on the position we reach at time k, so that should somehow be involved.

Continuous-Time Markov Chains

- $\circ \quad \mathbb{P}\left(X(s+t)=j\mid X(s)=i, X(r)=i_{j}, r\in A_{i}\subseteq [0,s)\right)=\mathbb{P}\left(X(s+t)=j\mid X(s)=i\right)$ o $\mathbb{P}\left(X(s+t)=j\mid X(s)=i\right)$ is a transition probability. We will typically as homogeneous transition probabilities: $\mathbb{P}\left(X(s+t)=j\mid X(s)=i\right)=\mathbb{P}\left(X(t)=j\mid X(0)=i\right)=P_{-}(t)$
- $\circ \quad \text{We define } \quad limiting \quad probabilities \quad \text{as} \quad \text{follows} \quad \alpha_{j} = \lim_{t \to r_{0}} P_{i,j}(t) = \lim_{t \to r_{0}} \mathbb{P}\left(X(t) = j \mid X(0) = i\right)$ Providing the chain is irreducible, α_c does not depend on the initial state.

- Modeling CTMCs We consider four methods of modeling CTMCs.
 - $\circ \quad \textit{Method 1-DTMC with Exponential Transition Times}$
 - Our first method involves modeling our CTMC as a DTMC in which the time till a transition out of state i is exponentially distributed with rate ν_i .
 - Though this is not necessary, we assume that there are no one-step transitions from any state to itself - in other words, the diagonal elements of the transition probabilities of the DTMC
 - (P.) are 0. o Method 2 - Transition Rates and ODEs
 - We define $Q_{i,j} = P'_{i,j}(0^+) = \lim_{t \downarrow 0} \frac{dP_{i,j}}{dt}$

It is more usual to define

$$\begin{split} P(0) &= I \\ P_{i,j}(h) &= Q_{i,j}h + o(h) \quad \text{ as } h \downarrow 0 \text{ if } j \neq i \\ P_{i,j}(h) - 1 &= Q_{i,j}h + o(h) \quad \text{ as } h \downarrow 0 \end{split}$$

For a finite state space, the above implies that $-Q_{i,i} = \sum_{j,j \neq i} Q_{i,j}$. Furthermore, since we have assumed $P_{\cdot,\cdot} = 0$ in the first approach, we have $-Q_{\cdot,\cdot} = \nu$.

 This kind of approach is useful when we have a rate diagram that shows the exponential rates of going from one step to another. Q_{ij} is then equal to the exponential rate of going from one state to another (with negative diagonal elements).

Method 3 - Competing Jobs with Exponential Timers

- . Method I worked because all crits from state i were exponentially distributed with the same ate ν_i . We generalize this to a case in which exits to different states have different
- For each state i, we associate a clock to each state j to which the process could move, and we let T_{ij} be the time at which that clock goes off. Whenever a clock goes off, we move to the corresponding state and reset all active clocks at the new state. By the lack-of-memory property of the exponential distribution, resetting running timers is equivalent to not resetting the times
- Let's analyze this. Let T = min (T) N = argmin (T).
 By the properties of the onential distribution, T_i and N_i are independent, and T_i - $Exp(\nu_i)$ and $P(N_i = j) = \frac{Q_{i,j}}{N_i}$

Where $\nu_i \equiv -Q_{i,i} = \sum_{i,i \neq i} Q_{i,j}$. As such, we can model our CTMC as a DTMC with transition probabilities Q_{c_i}/ν_c and waiting time ν_c

- We can also go the other way. Given a DTMC with transitions P and inter-transition times $\nu_{,}$, we can write $Q_{i,j}=\nu_{,}P_{i,j}$ $Q_{\scriptscriptstyle i,i} = -{\sum}_{\scriptscriptstyle j,j\neq i} Q_{\scriptscriptstyle i,j} = \nu_{\scriptscriptstyle i}$
- A CTMC is uniquely defined by a given Q. It is also uniquely defined by a given (P, \(\nu\)) provided $P_{ij} = 0$ (as we have assumed). Otherwise, we can transform our chain into one satisfying this property by defining a new DTMC transition matrix \hat{P} . We let $\hat{P}_c = 0$ and

$$\hat{P}_{i,j} = \mathbb{P}\left(i \text{ goes to } j \mid i \text{ doesn't go to } i\right) = \frac{P_{i,j}}{1 - P_{i,j}}$$

We the change the holding time at i to $\dot{\nu}_i > \nu_j$, to reflect the fact we removed "stay at i" transitions $1/\dot{\nu}_i = \frac{1/\nu_i}{1-P_i} \Rightarrow \dot{\nu}_i = \nu_i (1-P_{ij})$

Theorem: This leaves the chain unchanged.

Proof: Note that (1) transition rates determine transition probabilities (2) transition probabilities determine finite-dimensional distributions (3) finite-dimensional distributions are

• In each case, growths have $Q_{i,i+1} = \lambda$, except for state 5, which has growth 0 — this

• $Q_{_{1,0}}=\mu$, but all the other decreasing Q are $Q_{_{1,1-1}}=2\mu$ because two customers are being served at the same time.

The long run proportion of time each barber is busy, for example, can be found as $\frac{1}{6}\alpha_i + \alpha_s + \alpha_s + \alpha_s + \alpha_s$.

 Balking Consider the situation above, but in which an arriving customer finding both barbers taken will stay with probability β and balk otherwise.

 We then model this precisely as above, but the Poisson arrival proc $3 \rightarrow 4$ and $4 \rightarrow 5$ will be a thinned Poisson process, with rate $\beta\lambda$.

The PASTA (Poisson Arrivals See Time Averages) principle is also useful in calculating som-quantities of interest. It states that the proportion of customers that see some state upon arrival coincides with the proportion of times the process spends in that state, provided the arrival process is Poisson.

Thus, for example, the proportion of customers that balk is $(1-\beta)(\alpha_3+\alpha_4+\alpha_4)$. The proportion that are blocked is simply a_{\S} . And the proportion that enter upon arrival $-(1 - \beta)(\alpha_2 + \alpha_1 + \alpha_1) - \alpha_1$

- Abandoning Consider the situation above but in which any customer having to wait more than X for service will leave, where X - $\operatorname{Exp}(\theta)$.
 - The death rate for 1 → 0 is still u. The death rate for 2 → 1 is still 2u. The death rate for $3 \rightarrow 2$, however, is now $2\mu + \theta$, because it is the minimum of three var loss of patience and either barber finishing service. Similarly, the death rate $4 \rightarrow 3$ is $2\mu+2\theta$, because it is the minimum of four variables — either customer losing patience and either barber finishing.

The rate of customer abandonment can then be calculated as follows:

- . When the process is in 1 or 2, customers are not abandoned.
- When the process is in 3, abandonment occurs as $\operatorname{Exp}(\theta)$, and so customers are abandoned at rate θ per hour.
- When the process is in 4, customers are abandoned as $-\exp(2\theta)$, and so customers are abandoned at a rate 2θ per hour

Thus, the rate of customer abandonment is $\theta \alpha_s + 2\theta \alpha_t + 3\theta \alpha_c$. To find the proportion of customers that abandon, we just divide by the arrival rate.

Similarly, if we wanted to find the long-run proportion of potential customers eventually served, we could simply calculate 1 minus balking, blocking and abandoning. Another way is

ans of r, they're all as above. \overline{OF} is decreasing and convex as a function of q. (2) $\overline{B} = \lambda \overline{B} \overline{W}$ and $\overline{I} = \lambda \overline{I} \overline{W}$; application of Little's Law, and true not just for Poisson demands and constant leadtimes, provided the averages exist.

 Theorem: If BW denotes the limiting distribution of waiting times, and D(BW) denote the demand during hen if $r \ge -1$, B = D(BW). In particular, this gives $\mathbb{E}[B] = \lambda \mathbb{E}[BW]$ and $\lambda \mathbb{E}[BW] + \lambda^2 \mathbb{Vai}[BW]$.—can be shown that for a given $s \not= \mathbb{E}[B(B-1)] = G^2(s)$. We can weigh that across different s to get the quantity generally, and use that to find the variance of B.

• Exponential: $f(x) = \lambda e^{-\lambda x}$; $F(x) = 1 - e^{-\lambda x}$; $\mathbb{E} = \lambda^{-1}$; $\mathbb{V} = \lambda^{-2}$; $M(\theta) = \frac{\lambda}{\lambda - \theta}$. X ~ exp(λ). $Y \sim \exp(\mu)$: $min(X,Y) \sim exp(\lambda + \mu)$

 $\mathbb{P}(\min \ge z) = \mathbb{P}(X \text{ and } Y \ge z)$ $\max(X,Y) = (X+Y) - \min(X,Y)$: $\mathbb{P}(\min(X,Y) = X) = \lambda/(\lambda + \mu)$ $= \mathbb{P}(X < Y)$, condition on Y = Xand integrate]. $\{\min(X,Y) = X\} \perp \{\min(X,Y) > t\}$ [take $\mathbb P$ of both events, condition on X = x, integral then goes from $t \rightarrow \infty$].

• Normal: $f(\mathbf{x}) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left[-\frac{1}{2\sigma^2}(\mathbf{x} - \mu)^2\right]; \quad M(\theta) = \exp\left[\mu\theta + \frac{1}{2}\sigma^2\theta^2\right]; \quad \mathbb{B}[\mathbf{Z}^1] = 4, \quad \mathbb{E}[\mathbf{Z}^1] = 10$ $\tfrac{\sigma}{\sqrt{2\pi}}\Big(\!\tfrac{1}{x}-\!\tfrac{1}{x^2}\!\Big)e^{-x^2/2\sigma^2}\leq \overline{\Phi}(x)\leq \tfrac{\sigma}{\sqrt{2\pi}}\tfrac{1}{x}e^{-x^2/2\sigma^2};\;z\phi(z)=-\phi'(z).$

• Gamma (α, λ) : $f(x) = \frac{1}{\Gamma(a)} \lambda^{\alpha} x^{\alpha-1} e^{-\lambda x}$; $\mathbb{E} = \frac{\alpha}{\lambda}$; $\mathbb{V} = \frac{\alpha}{\lambda^2}$; $M(\theta) = (\frac{\lambda}{\lambda - \theta})^{\alpha}$; sum of α $\exp(\lambda)$ RV $\Gamma(n) = (n-1)!$

• Lognormal: $f(x) = \frac{1}{x}\phi(\log x)$; $F(x) = \Phi(\frac{1}{x}[\log x - \mu])$; $\mathbb{E} = \exp(\mu + \frac{1}{2}\sigma^2)$

• Beta: $x^{n-1}(1-x)^{\beta-1} / B(\alpha, \beta)$ mean $\alpha / (\alpha + \beta)$ variance $\alpha \beta / (\alpha + \beta)^2 (\alpha + \beta + 1)$

• Binomial: $\mathbb{P}(=k) = {}^nC_k p^k (1-p)^{n-k}$; $\mathbb{E} = np$; $\mathbb{V} = np(1-p)$; $M(\theta) = (1-p+pe^{\theta})^n$

• Negative binomial (r,p): Number of successes before r failures occur (success probability p). $\mathbb{P}(=k) = ^{k+r-1}C_k(1-p)^rp^k \text{ (support } 0,1,\ldots). \ \mathbb{E} = \frac{\rho r}{1-p} \text{ ; } \mathbb{V} = \frac{\rho r}{(1-\rho)^r} \text{ ; } M(\theta) = \left(\frac{1-\rho}{1-\rho^r}\right)^r \text{ (} \theta < -\log t \text{). When } r = 0$

• Poisson: $\mathbb{P}(=k) = \pm \lambda^k e^{-\lambda}$ sum of Poisson RVs results in sum of parameters (prove using MGF). Mean and variance λ . MGF $M(\theta) = \exp(\lambda(c^t - 1))$

 $\bullet \ \left(\tfrac{1}{x}-\tfrac{1}{x^i}\right)c^{-x^i-2} \leq \int_x^{r_0} c^{-y^i/2} \ \mathrm{d}y \leq \tfrac{1}{x}c^{-x^i/2}$

• $f(x) \sim g(x)$ if $\lim_{x \to \infty} \frac{f(x)}{g(x)} = 1$. Doesn't imply either function converges

• Hazard function is $\lambda(t) = f(t) \, / \, \overline{F}(t)$

 $\bullet \ \mathbb{C}\mathrm{ov}\left(X,Y\right) = \mathbb{E}\left\{(X - \mu_X)(Y - \mu_Y)\right\} = \mathbb{E}\left(XY\right) - \mathbb{E}\left(X\right)\mathbb{E}\left(Y\right)$ $\bullet \ \, \mathbb{V}\!\text{ar}\left(\sum\nolimits_{i}X_{i}\right) = \sum\nolimits_{i}\mathbb{V}\!\text{ar}(X_{i}) + 2\sum\nolimits_{i < j}\mathbb{C}\text{ov}(X_{i}, X_{j})$

the probability law of the CTMC. So all we need to show is that the transition rates are unchanged. $\hat{Q}_{i,j} = \dot{\nu}_i \hat{P}_{i,j} = \nu_i (1 - P_{i,i}) \frac{P_{i,j}}{1 - P_{i,i}} = \nu_i P_{i,j}$

○ Method 4 - A DTMC with Poisson Transitions

• Imagine, in the first approach, that all the ν_i were equal. In that case, we could represent our CTMC as a DTMC with transitions governed by an independent Poisson process. In fact, if the mean transition time is $1/\nu_n$ for all states, $\{Y_i : n \ge 0\}$ is a DTMC with transition $\text{matrix } P \text{ and } \left\{ N(t) \colon t \geq 0 \right\} \text{ is a Poisson process with rate } \nu_{\scriptscriptstyle 0} \text{, then } X(t) = Y_{\scriptscriptstyle N(t)} \qquad t \geq 0$

 $\text{And } P_{i,j}(t) = \mathbb{P}\left(X(t) = j \mid X(0) = i\right) = \sum_k P_{i,j}^k \mathbb{P}\left(N(t) = k\right) = \sum_k P_{i,j}^k \frac{e^{-i\phi^2}(\nu_0 t)^k}{k!}$

 Any finite-state CTMC can be represented in this way by uniform introducing fictitious transitions from states to themselves.

We generate potential transitions from a Poisson process with rate $\lambda \geq \nu_i \ \forall i$, and we then endently thin this Poisson process by making the transition a "real transition" with probability ν , $/\lambda$ and a "fictitious transition" with probability $1 - (\nu / \lambda)$

$$\tilde{P}_{i,j} = \frac{Q_{i,j}}{\lambda} \qquad \qquad \tilde{P}_{i,j} = 1 - \frac{\nu_i}{\lambda} = 1 - \frac{\sum_{j,j \neq i} Q_{i,j}}{\lambda} = 1 + \frac{Q_{i,j}}{\lambda}$$

Or, in matrix notation, $\tilde{P} = I + \lambda^{-1}Q$ Theorem: Performing the uniformization process above leaves the chain unchanged

- Limiting probabilities are not the same as stationary probabilities.
 - A limiting distribution is lim_{t-co} X(t)
 - A stationary distribution is a vector β such that $\mathbb{P}(X(t) = j) = \beta$, for all t and j whenever $P(X(0) = j) = \beta_i$.
- o Theorem: For irreducible, finite-state CTMC, the story is simpler. There exists a unique stationary vector, which is also a limiting vector
- We consider four methods for finding the limiting probabilities
 - transitions according to a Poisson process with rate λ

$$\alpha_j = \bar{\pi}_j \ \forall j$$

Where # is the unique solution to
$$\begin{split} \dot{\pi} &= \dot{\pi} \tilde{P} \\ \text{or } \sum_i \dot{\pi}_i \tilde{P}_{i,i} &= \dot{\pi}_i \end{split}$$

to note that the service rate is θ in state 1 and 2θ is other states, whereas the arrival rate is λ , so the total proportion served is $\frac{\theta\alpha_1+2\theta(\alpha_2+\alpha_3+\alpha_4+\alpha_5)}{\lambda}$. These give the same answer.

 The M/M/1 mene: Arrivals are rate λ, services times are - Exp(μ) and there are in infinite number of waiting spaces. The number of customers in the queue is Q(t), which is a birth-and-death process with infinite state space. To guard against pathologies, we require $\rho \equiv \lambda \, / \, \mu < 1$. Applying an obvious extension of the birth-and-death process in this case, we $\text{get } \alpha_j = \frac{r_j}{\sum_{i=1}^{\omega} r_i} \qquad \qquad r_j = \rho^j. \text{ This implies that } \alpha \text{ is the } \textit{geometric distribution} - \text{in other}$ words $\lim_{t\to\infty} \mathbb{P}\left(Q(t)=j\mid Q(0)=i\right)=\alpha_j=(1-\rho)\rho^j$ which has mean $\rho \mid (1-\rho)$.

If we had, instead, considered the M/M/I/r queuing model (with one server and r waiting spaces, we would have τ + 2 states with a truncated geometric distribution $\alpha_j = \frac{(1-\rho)}{\alpha_1 - e^{r+2\gamma}} \rho^j$ $0 \le j \le r+1$. This applies without limits on ρ .

• Reverse-time CTMC

- o A stochastic process $\{X(t): -\infty < t < \infty\}$ is said to be reversible if it has the same probability law as $\{X(-t): -\infty < t < \infty\}.$
- We define reverse transition probabilities as

$$\tilde{P}_{ij}(t) \equiv \mathbb{P}\left(X(s) = j \mid X(s+t) = i\right) = \frac{\mathbb{P}\left(X(s) = j\right)P_{ji}(t)}{\mathbb{P}\left(X(s+t) = i\right)}$$

Unfortunately, these do not necessarily need to be bona-fide probabilities that sum to 1. If, however, we start our chain with its stationary distribution α , the above becomes $\tilde{P}_{i,j}(t) = \frac{\alpha_j P_{j,i}(t)}{\alpha}$. Which, it can be shown, does sum to 1. Similarly, the transition-rate matrix for the reverse chain is $\tilde{Q}_{i,j} = \frac{\alpha_j Q_{j,i}}{\alpha_i}$

o This, however, is not enough for the chain to be time reversible. It can be shown that the extra required condition is for $\tilde{Q}=Q$, or equivalently $\alpha_iQ_{i,j}=\alpha_jQ_{j,i}$

Effectively, this requires all steady-state transitions from $i \rightarrow j$ to be equal to those from $j \rightarrow i$

It can be shown that all birth-and-death processes are reversible.

sider truncated processes, in which all transitions out of a subset of states $A \subseteq S$ at disallowed. In other words, we set $Q_{i,j} = 0$ for $i \in A, j \in S \setminus A$, and as usual, we set $Q_{i,j} = -\sum_{i \in A} Q_{i,j}$ Theorem: The truncated process is also reversible and has stationary probability vector

$$\alpha_j^{(\delta)} = \frac{\alpha_j}{\sum_{i \in I} \alpha_i} \qquad \forall j \in A \text{ where } \alpha \text{ in the stationary probability vector of the original process}$$

- When dealing with moments, recall that ∑_{i=0}[∞] z^o = (1 − z)⁻¹
- $\bullet \text{ Markov: } \mathbb{P} \left(X \geq a \right) \leq \mathbb{E} \left(X \right) / \, a \ [\, a \mathbb{I}_{X \geq a} \leq X \, , \, \text{take expectations}].$
- Jensen: E(f(x)) > f(E(X)) for convex f [take taylor series, second derivative +ve]
- Tail-integral formula: For a non-negative RV, $\mathbb{E}(X^a) = \int_0^\infty nt^{a-1}\overline{F}(t) dt$. For a non-negative integer value RV $\mathbb{E}(N)\sum_{i=1}^{\infty} \mathbb{E}(N \ge i)$.
- For conditional var, $\mathbb{V}ar(X) = \mathbb{E}(S^2) \mathbb{E}(S)^2$, write in conditional form, replace the first by $\mathbb{V}ar(S \mid N)$
- ${}^{a}C_{a} = n!/[k!(n-k)!]$
- MGF: $M(t) = \mathbb{E}[e^{tX}]$ and CF = M(it)
- The k^n order statistic of n U[0,1] RVs is B(k, n+1-k)
- $\bullet \text{ Geometric: } \sum_{k=0}^{n-1} ar^k = a\frac{1-r^n}{1-r},$
- Law of total variance: $var(Y) = E(var(Y \mid X)) + var(E(Y \mid X))$

• a_n and b_n only positive and $a_n / b_n \rightarrow L \neq 0$ then if sum b_n converges, so does sum a_n . An example of this is if a_n

If 0 < lim a... / a. < 1, then sum a. converges

Two possibly non real sequences a_n and b_v If $a_n \to \theta$ and $b_n \to \inf$ infty and $a_nb_n \to c$ then $(1+a_n)^{i_{n-1}} \to c^i$ $\bullet \text{ If } \lim_{n \to -\tau} f(x) = l \text{ and } \lim_{n \to +\tau} g(x) = L \text{ then } \lim_{n \to +\tau} g(f(x)) = L, \text{ provided } g \text{ defined and continuous at } l$

• $\sum 1/n^2 = \pi^2/6$

Introduction

• Definition (Strong Stationarity): The process $\{X(t): t \ge 0\}$ is stationary if

 $\left(X(t_{\scriptscriptstyle \parallel}),X(t_{\scriptscriptstyle \parallel}),\cdots,X(t_{\scriptscriptstyle \parallel})\right) = \left(X(t_{\scriptscriptstyle \parallel}+n),X(t_{\scriptscriptstyle \parallel}+n),\cdots,X(t_{\scriptscriptstyle \parallel}+n)\right)$ For all $t_i < t_i < \cdots < t_s$ and $n \ge 0$. In other words, a process is stationary if it is "shift invariant"

- Definition (Weak Stationarity): The process {X(t): t≥0} is said to be covariance station $\mathbb{E}\big[X(t)\big] = m \ \ (\text{ie: it has constant mean}) \ \ \text{and} \ \ \mathbb{C}\text{ov}\big[X(t),X(s)\big] = \mathbb{E}\big[(X(t)-m)(X(s)-m)\big] = R\big(\big[t-s\big]\big), \ \ \text{where} \ \ R = \mathbb{E}\big[(X(t)-m)(X(s)-m)\big] = R\big(\big[t-s\big]\big)$
- Note that a Gaussian process is entirely defined by its mean and covariance; as such, for a Gaussian prostationarity implies covariance stationarity.

 Theorem: Give a CTMC characterized in terms of a DTMC with one-step transition matrix P and exponential transition times with means $1 / \nu_i$

$$\alpha_j = \frac{\pi_j / \nu_j}{\sum_k \pi_k / \nu_k}$$

Where π is the unique solution is

$$\pi = \pi P$$
 $\pi I = 1$

Theorem: Given a CTMC characterized by its transition-rate matrix Q, α is the unique

$$\alpha Q = 0$$
 $\alpha t = 1$
or $\sum_i \alpha_i Q_{i,j} = 0$ $\sum_i \alpha_i = 1$

These are "global-balance equations" - all probabilities of transition into a state must be equal to transitions out of it.

Theorem: Given a CTMC characterized by its transition function P(t), α is the unique.

$$\begin{array}{ll} \alpha P(t) = \alpha \text{ for any } t > 0 & \qquad \alpha \mathbf{1} = 1 \\ \sum_i \alpha_i P_{i,j}(t) = \alpha_j \text{ for all } j & \qquad \sum_i \alpha_i = 1 \end{array}$$

• Birth and Death Processes

- o Birth and death processes are those in which only transitions up and down one state is possible. In such processes, the global-balance equations $\alpha Q=0$ take the simpler form of detailed-balance
- o $\it Theorem$: For birth-and-death processes, the limiting probability vector α is the unique solution to the detailed-balance equations $\alpha_j \lambda_j = \alpha_{j+1} \mu_{j+1} \ \forall \ 0 \leq j \leq n-1$. With $\alpha I = 1$. This reflects
- conservation of flow again; transitions from j to j + 1 must be equal to transitions from j + 1 to j.

$$\alpha_j = \frac{r_j}{\sum_{i=0}^n r_i} \qquad \qquad 0 \leq j \leq n \text{ where } r_0 = 1 \qquad \qquad r_j = \frac{\lambda_j \lambda_1 \cdots \lambda_{j-1}}{\mu_i \mu_2 \cdots \mu_j}$$

Proof. We simply note that the detailed balance equations require that $\alpha_j = \frac{\lambda_{j-1}}{\mu} \alpha_{j-1}$ and so

 $\alpha = r \alpha_o$. This is precisely the above. To get the final form, we use the fact that $\alpha I = 1$

- Assorted examples and applications
 - Blocking: Consider a barbershop with two chairs (exponential services times of rate μ) and three waiting spaces. Customers arrive at Poisson λ . Any customers arriving when both waiting chairs are full are lost:
 - This is a hirth-and-death process with states 0 1 2 3 4 and 5

• The departures from an M/M/s queue (with $\rho \equiv \lambda \ / \ s\mu < 1$) in equilibrium is also a Poisson process, with departure rate equal to λ . To see why, simply note the CTMC consisting of the number of people in the queue = Q(t) — is a reversible CTMC. Running it backwards changes arrivals into departures.

- Notation: \(\Lambda \) is the demand rate, \(L \) is the order lead time, \(q \) is the batch size, \(r \) is the re-order point, \(B(t, q) \) is the demand in that interval, \(I(t) = IN(t)^* \) is the inventory on hand, \(B(t) = IN(t)^* \) are the backwiders outstanding, \(IN(t) = I(t) B(t) \) is the net inventory, \(A(t) \) is the steckout indicator \(I(EN(t) \leq 0), \(IO(t) \) is the restriction. inventory on order, IP(t) = IN(t) + IO(t) is the inventory position.
- mercany out ones, $T_i = E(i) E(i) + E(i)$ are unreading placed and are represented by E(i) = E(i) E(i) and E(i) = E(i) are represented frequency. E(i) = E(i) are represented frequency. E(i) = E(i) are represented frequency. E(i) = E(i) and E(i) = E(i) are represented frequency. E(i) = E(i) are represented frequency.
- General strategy; find IN (for which we need IP and D) and use it to find I, A and B
- General states t_i , and t_i (or when t_i we see it t_i and t_j) and t_i the label of t_i in t_i at t_i and t_j and t_j the label of t_j and t_j and t_j are t_j and t_j and t_j and t_j are t_j and t_j and t_j are t_j and t_j and t_j and t_j are t_j and t_j and t_j and t_j are t_j and t_j are t_j and t_j and t_j are t_j and t_j are t_j are t_j and t_j are t_j are t_j and t_j are t_j are
- Performance measures. The q denote the PMF (probability mass function) of D, G its inverse CDF and
 $$\begin{split} G^{\downarrow}(d) &= \mathbb{E}[(D-d)^{\dagger}] = \sum_{j \in [d+1,n]} G^{\emptyset}(j) = \lambda L - \sum_{j \in [0,d]} G^{\emptyset}(j), \\ \overline{A} &= \mathbb{P}(IN \leq 0) = \mathbb{P}(D \geq s) = G^{\emptyset}(s-1). \end{split}$$
 We $\overline{B} = \mathbb{E}[IN^{-}] = \mathbb{E}[(D - s)^{+}] = G^{1}(s).$ $\overline{I} = \mathbb{E}[IN^+] = \mathbb{E}[IN^+|IN^-] = s - \lambda L + G^{\dagger}(s)$. Of course, $\overline{OF} = \lambda$. For Poisson demands, \overline{A} is also the
- $I = \mathbb{B}(N^+ | \mathbb{B}(N^+ | N^-) = s^- \lambda h + G^*(s)$. Of course, $OF = \lambda$. For Poisson demands, A is also the proportion of demands that ends up having to wait $(P, PSATA, \hat{B}^T) = \hat{\beta}/\lambda$ is the average cutomer waiting time and $\widehat{DV} = I/\lambda$ is the average stocking time (the time a unit spends in inventory). Notes: (1) Everything only depends on λL . (2) \widehat{B} is decreasing and convex as function of s (3) \widehat{I} is increasing and convex in s (1) \widehat{A} be decreasing in s and convex convex the $\lambda L L$ plus third \widehat{I} (Gind Corresponding DYMC) (B) IN(t+L) = IP(t) - D(t, t+L) (IN at t+L is equal to IN at t plus IO at t; which will get there by t+L)
- Performance measures. Now, we know [IN | IP = s] is as given in the base-stock policy. But we know the distribution of IP is uniform. So, for eg. $\overline{A}(r,q) = \frac{1}{2}\sum_{i=0}^{n-1} A(s)$. Same is true for \overline{B} and \overline{I} . Witting $G^{s}(d) = \sum_{i=0}^{n} G^{s}(f) = \frac{1}{2}(\Delta I)^{s} - \sum_{i\geq 0} G^{s}(f)$, we also have $\overline{A} = \frac{1}{4}|G^{s}(r) - G^{s}(r+q)|$, $\overline{B} = \frac{1}{4}|G^{s}(r) - G^{s}(r+q)|$ and $\overline{I} = \frac{1}{4}(q+1) - r - \lambda L + \overline{B}$. $\overline{OF} = \lambda/q$ since orders come in at rate λ and orders are made every q

Theorems

- Theorem (Weak Ergodic Theorem): If $\{X_n\}$ is covariance stationary, then $\overline{X}_n \to_L \overline{X}$, where $\overline{X}_{v} = \frac{1}{n} \sum_{i=1}^{n} X_{i}$. Note that in general, \overline{X} will be a random variable. Under one of two equivalent conditions
- it is a deterministic constant equal to $\mathbb{E}(X_{\cdot}) = m$:
- \circ Cov $(\overline{X}_*, X_*) \rightarrow 0$
- Theorem (Strong Ergodic Theorem): If $\{X_n\}$ is stationary and $X_n \in L_1$, then $\overline{X}_n \to \overline{X}$ a.s. and $\overline{X}_{\circ} \rightarrow_{c} \overline{X}$. Again, \overline{X} is generally a random variable. Under cryodicity (defined below), it is constant. An ntermediate step in proving this is...

Lemma (Maximal Ergodic Lemma): Let $\{Y\}$ be stationary and let $S = Y + \cdots + Y$. . and $M_{_{i,a}} = \max\left\{0, S_{_{i,1}}, \cdots, S_{_{i,n}}\right\}. \text{ Then } \mathbb{E}[Y_0Y1_{\{M_{_0,n}>0\}}] \geq 0 \ \forall n \geq 1.$

Definition (Shift Operator): φ is a shift operation. If $x = (x_1, x_2, \cdots)$ then $\varphi(x) = (x_2, x_2, \cdots)$. We say the set A is shift invariant if $x = A \Rightarrow \varphi(x) \in A$. For example, the following two sets are shift invariant (we can replace \underline{x} by \underline{x} and \underline{x} , and \underline{x} lim sup by \underline{x} lim inf)

$$\geq$$
 and $=$, and \lim sup by \lim inf)

$$A_1 = \left\{ x : \lim_{n \to \infty} \frac{z_1 + \dots + z_r}{c} \leq a \right\}$$

$$A_2 = \left\{ x : \lim\sup_{n \to \infty} \frac{z_1 + \dots + z_r}{c} \leq a \right\}$$

Definition (Ergodicity): X = (X₁,···, X_s,···) is ergodic if \(\tilde{\Pi}(X \in A) = 0 \) or 1 for all shift invariant A.
 Note: We can use this definition of ergodicity to show that \(\tilde{X} \) is constant.

 $\mathbb{P}(X \in A) = \mathbb{P}(\lim_{n \to \infty} \overline{X} \le a) =_{nn} \mathbb{P}(\overline{X} \le a) = 0 \text{ or } 1$

Definition (Mixing): $X = \{X_1, X_2, \dots, X_n, \dots\}$ is mixing if $\lim_{n \to \infty} \mathbb{P} \big((X_1, X_2, \cdots) \in A_i(X_{n+1}, X_{n+2}, \cdots) \in A \big) = \mathbb{P} \big((X_1, X_2, \cdots) \in A \big) \cdot \mathbb{P} \big((X_1, X_2, \cdots) \in A \big)$ Where A and B are sets of infinite sequences (not necessarily shift invariant). We can look at pieces of size k

instead $\lim_{n \to \infty} \mathbb{P}((X_n, \dots, X_{n+1}) \in A, (X_{n+n}, \dots, X_{n+n+1}) \in B).$ Theorem: If a sequence is mixing, it is ergodic

Proof. Let A be any shift invariant set

invariant set
$$\begin{split} p &= \mathbb{P}\left((X_0, X_1, \cdots) \in A\right) \\ &= _{A \text{ oth invaries }} \mathbb{P}\left((X_0, X_1, \cdots) \in A, (X_n, X_{n+1}, \cdots) \in A\right) \\ &\xrightarrow[]{} &\xrightarrow[]{} &\xrightarrow[]{} & \text{more } \mathbb{P}\left((X_0, X_1, \cdots) \in A\right) : \mathbb{P}\left((X_0, X_1, \cdots) \in A\right) \\ &= p^1 \end{split}$$

And so p must be equal to 0 or 1

• Example: Let $X_0 = Y$ w.p. p and Z w.p. 1-p, where $Y,Z \in L_1$. Consider two cases of $X_n = X_0$, $\overline{X} = Y$ w.p. p and Z w.p. 1-p

o. If $X_{_0}=_{_d}X_{_0},\ \overline{X}=\mathbb{E}(Y)$ w.p. p and $\mathbb{E}(Z)$ w.p. 1-p